Isolated, Regulated DC Converter

**Features**

- Isolated, regulated DC-to-DC converter
- Up to 600 W, 43.5 A continuous
- 93% peak efficiency
- 1239 Win³ Power density
- Wide extended input range 160 – 420 Vdc
- Safety Extra Low Voltage (SELV) 13.8 V Nominal Output
- 4242 Vdc isolation
- ZVS high frequency (MHz) switching
  - Enables low-profile, high-density filtering
- Optimized for array operation
  - Up to 8 units – 4800 W
  - No power derating needed
  - Sharing strategy permits dissimilar line voltages across an array
- Fully operational current limit
- OV, OC, UV, short circuit and thermal protection
- 4623 through-hole ChiP package
  - 1.886“ x 0.898” x 0.286”
  - (47.91 mm x 22.8 mm x 7.26 mm)

**Typical Applications**

- Transportation
- Industrial Systems
- Electric Vehicle (EV) / Hybrid Electric Vehicle (HEV)
- On-board Power

**Product Ratings**

<table>
<thead>
<tr>
<th>Operating Input (V)</th>
<th>Output Power Max (W)</th>
<th>Output (V) set point 100% load, 25°C</th>
</tr>
</thead>
<tbody>
<tr>
<td>Min</td>
<td>Nom</td>
<td>Max</td>
</tr>
<tr>
<td>200</td>
<td>290</td>
<td>378</td>
</tr>
<tr>
<td>160</td>
<td>420</td>
<td>500</td>
</tr>
</tbody>
</table>

**Product Description**

The DCM Isolated, Regulated DC Converter is a DC-to-DC converter, operating from an unregulated, wide range input to generate an isolated 13.8 Vdc output. With its high frequency zero voltage switching (ZVS) topology, the DCM converter consistently delivers high efficiency across the input line range. Modular DCM converters and downstream DC-DC products support efficient power distribution, providing superior power system performance and connectivity from a variety of unregulated power sources to the point-of-load.

Leveraging the thermal and density benefits of Vicor’s ChiP packaging technology, the DCM module offers flexible thermal management options with very low top and bottom side thermal impedances. Thermally-adept ChiP based power components enable customers to achieve cost effective power system solutions with previously unattainable system size, weight and efficiency attributes, quickly and predictably.
Typical Application

Typical Application 1: DCM290P138T600A40 for EV/HEV applications

Typical Application 2: DCM290P138T600A40 + Picor Point-of-Load
### Pin Configuration

**4623 ChiP Package**

### Pin Descriptions

<table>
<thead>
<tr>
<th>Pin Number</th>
<th>Signal Name</th>
<th>Type</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>A1</td>
<td>+IN</td>
<td>INPUT POWER</td>
<td>Positive input power terminal</td>
</tr>
<tr>
<td>B1</td>
<td>TR</td>
<td>INPUT</td>
<td>Enables and disables trim functionality. Adjusts output voltage when trim active.</td>
</tr>
<tr>
<td>C1</td>
<td>EN</td>
<td>INPUT</td>
<td>Enables and disables power supply</td>
</tr>
<tr>
<td>D1</td>
<td>FT</td>
<td>OUTPUT</td>
<td>Fault monitoring</td>
</tr>
<tr>
<td>E1</td>
<td>-IN</td>
<td>INPUT POWER RETURN</td>
<td>Negative input power terminal</td>
</tr>
<tr>
<td>A', 2, C', 2</td>
<td>+OUT</td>
<td>OUTPUT POWER</td>
<td>Positive output power terminal</td>
</tr>
<tr>
<td>B', 2, D', 2</td>
<td>-OUT</td>
<td>OUTPUT POWER RETURN</td>
<td>Negative output power terminal</td>
</tr>
</tbody>
</table>
**Part Ordering Information**

<table>
<thead>
<tr>
<th>Device</th>
<th>Input Voltage Range</th>
<th>Package Type</th>
<th>Output Voltage x 10</th>
<th>Temperature Grade</th>
<th>Output Power</th>
<th>Revision</th>
<th>Version</th>
</tr>
</thead>
<tbody>
<tr>
<td>DCM</td>
<td>290</td>
<td>P</td>
<td>138</td>
<td>T</td>
<td>600</td>
<td>A4</td>
<td>0</td>
</tr>
<tr>
<td>DCM = DCM</td>
<td>290 = 160 to 420 V</td>
<td>P = ChiP TH</td>
<td>138 = 13.8 V</td>
<td>T = -40 to 125°C</td>
<td>600 = 600 W</td>
<td>A4</td>
<td>Analog Control Interface Version</td>
</tr>
</tbody>
</table>

**Standard Models**

<table>
<thead>
<tr>
<th>Part Number</th>
<th>VIN</th>
<th>Package Type</th>
<th>VOUT</th>
<th>Temperature</th>
<th>Power</th>
<th>Version</th>
</tr>
</thead>
<tbody>
<tr>
<td>DCM290P138T600A40</td>
<td>160 to 420 V</td>
<td>ChiP TH</td>
<td>13.8 V (11.5 to 15.5 V)</td>
<td>T = -40 to 125°C</td>
<td>600 W</td>
<td>Analog Control Interface Version</td>
</tr>
</tbody>
</table>

**Absolute Maximum Ratings**

The absolute maximum ratings below are stress ratings only. Operation at or beyond these maximum ratings can cause permanent damage to the device. Electrical specifications do not apply when operating beyond rated operating conditions.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Comments</th>
<th>Min</th>
<th>Max</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>Input Voltage (+IN to –IN)</td>
<td>Continuous</td>
<td>-0.5</td>
<td>460</td>
<td>V</td>
</tr>
<tr>
<td></td>
<td>100 ms with a maximum duty cycle of 10%</td>
<td>-0.5</td>
<td>550</td>
<td>V</td>
</tr>
<tr>
<td>Input Voltage Slew Rate</td>
<td></td>
<td>-1</td>
<td>1</td>
<td>V/μs</td>
</tr>
<tr>
<td>TR to - IN</td>
<td></td>
<td>-0.3</td>
<td>3.5</td>
<td>V</td>
</tr>
<tr>
<td>EN to -IN</td>
<td></td>
<td>-0.3</td>
<td>3.5</td>
<td>V</td>
</tr>
<tr>
<td>FT to -IN</td>
<td></td>
<td>-0.3</td>
<td>3.5</td>
<td>V</td>
</tr>
<tr>
<td>Output Voltage (+Out to –Out)</td>
<td>Reinforced insulation</td>
<td>-0.5</td>
<td>25</td>
<td>V</td>
</tr>
<tr>
<td>Dielectric withstand (input to output)</td>
<td>Reinforced insulation</td>
<td>4242</td>
<td>Vdc</td>
<td></td>
</tr>
<tr>
<td>Temperature</td>
<td>Operating Internal</td>
<td>-40</td>
<td>125</td>
<td>°C</td>
</tr>
<tr>
<td>Storage</td>
<td></td>
<td>-40</td>
<td>125</td>
<td>°C</td>
</tr>
<tr>
<td>Average Output Current</td>
<td></td>
<td>51</td>
<td></td>
<td>A</td>
</tr>
</tbody>
</table>

**Thermal Specified Operating Area: Max Output Power vs. Case Temp, Single unit at minimum full load efficiency**
## Electrical Specifications

Specifications apply over all line in \( V_{IN-EXTENDED} \), trim and load conditions, internal temperature \( T_{INT} = 25^\circ C \), unless otherwise noted. **Boldface** specifications apply over the temperature range of \(-40^\circ C < T_{INT} < 125^\circ C\).

<table>
<thead>
<tr>
<th>Attribute</th>
<th>Symbol</th>
<th>Conditions / Notes</th>
<th>Min</th>
<th>Typ</th>
<th>Max</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>Power Input Specification</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Input Voltage Range, full power</td>
<td>( V_{IN} )</td>
<td>Module will only startup if input voltage is inside the range of ( V_{IN} ). After startup, Module can then operate in the entire ( V_{IN-EXTENDED} ) range</td>
<td>200</td>
<td>290</td>
<td>378</td>
<td>V</td>
</tr>
<tr>
<td>Input Voltage Range, extended</td>
<td>( V_{IN-EXTENDED} )</td>
<td></td>
<td>160</td>
<td>290</td>
<td>420</td>
<td>V</td>
</tr>
<tr>
<td>Inrush current (peak)</td>
<td>( I_{INRP} )</td>
<td>With maximum ( C_{OUT-EXT} ), full resistive load</td>
<td>8.5</td>
<td>A</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Input capacitance (internal)</td>
<td>( C_{IN-INT} )</td>
<td>Effective value at nominal input voltage</td>
<td>0.8</td>
<td>( \mu F )</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Input capacitance (internal) ESR</td>
<td>( R_{CIN-INT} )</td>
<td>At 1 MHz</td>
<td>2.5</td>
<td>( m\Omega )</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Input inductance (external)</td>
<td>( L_{IN} )</td>
<td>Differential mode, with no further line bypassing</td>
<td>10</td>
<td>( \mu H )</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Input capacitance (external)</td>
<td>( C_{IN-EXT} )</td>
<td>Effective value at nominal input voltage</td>
<td>0.68</td>
<td>( \mu F )</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

### No Load Specification

<table>
<thead>
<tr>
<th>Attribute</th>
<th>Symbol</th>
<th>Conditions / Notes</th>
<th>Min</th>
<th>Typ</th>
<th>Max</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>Input power – disabled</td>
<td>( P_Q )</td>
<td>Nominal line, see Fig. 2</td>
<td>0.7</td>
<td>1.5</td>
<td>W</td>
<td></td>
</tr>
<tr>
<td>Input power – enabled with no load</td>
<td>( P_{NL} )</td>
<td>Nominal line, see Fig. 3</td>
<td>2</td>
<td>3</td>
<td>W</td>
<td></td>
</tr>
</tbody>
</table>

### Power Output Specification

<table>
<thead>
<tr>
<th>Attribute</th>
<th>Symbol</th>
<th>Conditions / Notes</th>
<th>Min</th>
<th>Typ</th>
<th>Max</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td>Output voltage set point</td>
<td>( V_{OUT-NOM} )</td>
<td>( V_{IN} = 290 ) V, trim inactive, at 100% Load, ( T_{INT} = 25^\circ C )</td>
<td>13.66</td>
<td>13.8</td>
<td>13.94</td>
<td>V</td>
</tr>
<tr>
<td>Output voltage trim range</td>
<td>( V_{OUT-TRIMMING} )</td>
<td>Linear range over temp, with &gt; 5% rated load. Specifies the Low, Nominal and High Trim conditions.</td>
<td>11.5</td>
<td>13.8</td>
<td>15.5</td>
<td>V</td>
</tr>
<tr>
<td>Output voltage load regulation</td>
<td>( \Delta V_{OUT-LOAD} )</td>
<td>Linear load line. Output voltage increase from full rated load current to no load (Does not include light load regulation). See Fig. 5 and Sec. Design Guidelines</td>
<td>0.6503</td>
<td>0.7263</td>
<td>0.8032</td>
<td>V</td>
</tr>
<tr>
<td>Output voltage light load regulation</td>
<td>( \Delta V_{OUT-LL} )</td>
<td>0% to 5% Load, additional ( V_{OUT} ) relative to calculated load line point; see Fig. 5 and Sec. Design Guidelines</td>
<td>0.0</td>
<td>2.3</td>
<td>V</td>
<td></td>
</tr>
<tr>
<td>Output voltage temperature coefficient</td>
<td>( \Delta V_{OUT-TEMP} )</td>
<td>Nominal, linear temperature coefficient, relative to ( T_{INT} = 25^\circ C ). See Fig. 4 and Sec. Design Guidelines</td>
<td>-1.84</td>
<td>mV/°C</td>
<td></td>
<td></td>
</tr>
<tr>
<td>( V_{OUT} ) accuracy</td>
<td>%( V_{OUT-ACCURACY} )</td>
<td>The total output voltage setpoint accuracy from the calculated ideal ( V_{OUT} ) based on load, temp and trim. Excludes ( \Delta V_{OUT-LL} )</td>
<td>2.00</td>
<td>%</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Rated output power</td>
<td>( P_{OUT} )</td>
<td>Continuous, ( V_{OUT} \approx 13.8 ) V, 200 V ( \leq V_{IN} \leq 378 ) V</td>
<td>600</td>
<td>W</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Rated output current</td>
<td>( I_{OUT} )</td>
<td>Continuous, ( V_{OUT} \approx 13.8 ) V, 200 V ( \leq V_{IN} \leq 378 ) V</td>
<td>43.5</td>
<td>A</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Derated output power</td>
<td>( P_{OUT-DERATED} )</td>
<td>Continuous, ( V_{OUT} \approx 13.8 ) V, ( 160 &lt; V_{IN} &lt; 200 ) or ( 378 &lt; V_{IN} &lt; 420 ) V</td>
<td>500</td>
<td>W</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Derated output current</td>
<td>( I_{OUT-DERATED} )</td>
<td>Continuous, ( V_{OUT} \approx 13.8 ) V, ( 160 &lt; V_{IN} &lt; 200 ) or ( 378 &lt; V_{IN} &lt; 420 ) V</td>
<td>36.2</td>
<td>A</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Output current limit</td>
<td>( I_{OUT-LM} )</td>
<td>Of ( I_{OUT} ) max. Fully operational current limit</td>
<td>100</td>
<td>105</td>
<td>117</td>
<td>%</td>
</tr>
<tr>
<td>Current limit delay</td>
<td>( t_{OUT-LM} )</td>
<td>The module will power limit in a fast transient event</td>
<td>1</td>
<td>ms</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Efficiency</td>
<td>( \eta )</td>
<td>Full Load, Nominal Line, trim inactive</td>
<td>92.9</td>
<td>93.6</td>
<td>%</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>Full Load, over ( V_{IN} ) and temperature, trim inactive</td>
<td>91.5</td>
<td>%</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>Full Load, over ( V_{IN-EXTENDED} ) and temperature, trim inactive</td>
<td>91.0</td>
<td>%</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>50% Load, over line, temperature and trim</td>
<td>90.0</td>
<td>%</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Output voltage ripple</td>
<td>( V_{OUT-PP} )</td>
<td>Over all operating steady-state load, and trim conditions, 20 MHz BW, with minimum ( C_{OUT-EXT} )</td>
<td>500</td>
<td>mV</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
**Electrical Specifications (cont.)**

Specifications apply over all line in $V_{IN-EXTENDED}$, trim and load conditions, internal temperature $T_{INT} = 25^\circ C$, unless otherwise noted. **Boldface** specifications apply over the temperature range of $-40^\circ C < T_{INT} < 125^\circ C$.

<table>
<thead>
<tr>
<th>Attribute</th>
<th>Symbol</th>
<th>Conditions / Notes</th>
<th>Min</th>
<th>Typ</th>
<th>Max</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Power Output Specifications (Cont.)</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Output capacitance (internal)</td>
<td>$C_{OUT-INT}$</td>
<td>Effective value at nominal output voltage</td>
<td>72</td>
<td>µF</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Output capacitance (internal) ESR</td>
<td>$R_{COUT-INT}$</td>
<td>At 1MHz</td>
<td>0.06</td>
<td>mΩ</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Output capacitance (external)</td>
<td>$C_{OUT-EXT}$</td>
<td>Electrolytic Capacitor preferred. Excludes component tolerances and temperature coefficient</td>
<td>1000</td>
<td>µF</td>
<td>10000</td>
<td>µF</td>
</tr>
<tr>
<td>Output capacitance, ESR (ext.)</td>
<td>$R_{COUT-EXT}$</td>
<td>At 10 kHz, excludes component tolerances</td>
<td>10</td>
<td>mΩ</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Initialization delay</td>
<td>$t_{IN}$</td>
<td>After input voltage first exceeds $V_{IN-INIT}$</td>
<td>25</td>
<td>40</td>
<td>ms</td>
<td></td>
</tr>
<tr>
<td>Output turn-on delay</td>
<td>$t_{ON}$</td>
<td>From rising edge $EN$, with $VIN$ pre-applied. See timing diagram</td>
<td>200</td>
<td>µs</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Output turn-off delay</td>
<td>$t_{OFF}$</td>
<td>From falling edge $EN$. See timing diagram</td>
<td>600</td>
<td>µs</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Start-up setpoint acquisition time</td>
<td>$t_{SS}$</td>
<td>Full load (soft-start ramp time) with minimum $C_{OUT-EXT}$</td>
<td>5.0</td>
<td>ms</td>
<td></td>
<td></td>
</tr>
<tr>
<td>$V_{OUT}$ threshold for max rated load current</td>
<td>$V_{OUT-FL-THRESH}$</td>
<td>During startup, $V_{OUT}$ must achieve this threshold before output can support full rated current</td>
<td>10.5</td>
<td>V</td>
<td></td>
<td></td>
</tr>
<tr>
<td>$I_{OUT}$ at startup</td>
<td>$I_{OUT-START}$</td>
<td>Max load current at startup while $V_{OUT}$ is below $V_{OUT-FL-THRESH}$</td>
<td>0.1</td>
<td>A</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Monotonic soft-start threshold voltage</td>
<td>$V_{OUT-MONOTONIC}$</td>
<td>At startup, the DCM output voltage rise becomes monotonic with a minimum of 25% pre-load once it crosses $V_{OUT-MONOTONIC}$, standalone or as a member in an array</td>
<td>10.5</td>
<td>V</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Minimum required disabled duration</td>
<td>$t_{OFF-MIN}$</td>
<td>This refers to the minimum time a module needs to be in the disabled state before it will attempt to start via $EN$</td>
<td>2</td>
<td>ms</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Minimum required disabled duration for predictable restart</td>
<td>$t_{OFF-MONOTONIC}$</td>
<td>This refers to the minimum time a module needs to be in the disabled state before it is guaranteed to exhibit monotonic soft-start and have predictable startup timing</td>
<td>100</td>
<td>ms</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Voltage deviation (transient)</td>
<td>$%V_{OUT-TRANS}$</td>
<td>$C_{OUT-EXT} = \min$; (10 ↔ 90% load step), excluding load line. Load slew rate &lt; 43.5 A/ms</td>
<td>&lt;10</td>
<td>%</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Settling time</td>
<td>$t_{SETTLE}$</td>
<td></td>
<td>&lt;0.5</td>
<td>ms</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Powertrain Protections</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Input Voltage Initialization threshold</td>
<td>$V_{IN-INIT}$</td>
<td>Threshold to start $t_{IN}$ delay</td>
<td>75</td>
<td>V</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Input Voltage Reset threshold</td>
<td>$V_{IN-RESET}$</td>
<td>Latching faults will clear once $VIN$ falls below $V_{IN-RESET}$</td>
<td>50</td>
<td>V</td>
<td></td>
<td></td>
</tr>
<tr>
<td>$VIN$ undervoltage Turn-OFF</td>
<td>$V_{IN-UVLO-}$</td>
<td></td>
<td>130</td>
<td>155</td>
<td>V</td>
<td></td>
</tr>
<tr>
<td>$VIN$ undervoltage Turn-ON</td>
<td>$V_{IN-UVLO+}$</td>
<td>See Timing diagram</td>
<td>200</td>
<td>V</td>
<td></td>
<td></td>
</tr>
<tr>
<td>$VIN$ overvoltage Turn-OFF</td>
<td>$V_{IN-OVLO-}$</td>
<td></td>
<td>450</td>
<td>V</td>
<td></td>
<td></td>
</tr>
<tr>
<td>$VIN$ overvoltage Turn-ON</td>
<td>$V_{IN-OVLO+}$</td>
<td>See Timing diagram</td>
<td>380</td>
<td>V</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Output overvoltage threshold</td>
<td>$V_{OUT-OVP}$</td>
<td>From 25% to 100% load. Latched shutdown. Primary sensed output voltage only</td>
<td>17.2</td>
<td>V</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Output overvoltage threshold</td>
<td>$V_{OUT-OVP-LL}$</td>
<td>From 0% to 25% load. Latched shutdown. Primary sensed output voltage only</td>
<td>18.0</td>
<td>V</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Minimum current limited $VOUT$</td>
<td>$V_{OUT-OVP}$</td>
<td>Over all operating steady-state line and trim conditions</td>
<td>6</td>
<td>V</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Overtemperature threshold (internal)</td>
<td>$T_{INT-OTP}$</td>
<td></td>
<td>125</td>
<td>°C</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Power limit</td>
<td>$P_{UL}$</td>
<td></td>
<td>880</td>
<td>W</td>
<td></td>
<td></td>
</tr>
<tr>
<td>$VIN$ overvoltage to cessation of powertrain switching</td>
<td>$t_{OVL-SW}$</td>
<td>Independent of fault logic</td>
<td>1</td>
<td>µs</td>
<td></td>
<td></td>
</tr>
<tr>
<td>$VIN$ overvoltage response time</td>
<td>$t_{OVL}$</td>
<td>For fault logic only</td>
<td>200</td>
<td>µs</td>
<td></td>
<td></td>
</tr>
<tr>
<td>$VIN$ undervoltage response time</td>
<td>$t_{UVL}$</td>
<td></td>
<td>100</td>
<td>ms</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Short circuit response time</td>
<td>$t_{SC}$</td>
<td>Powertrain on, operational state</td>
<td>200</td>
<td>µs</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Short circuit, or temperature fault recovery time</td>
<td>$t_{FAULT}$</td>
<td>See Timing diagram</td>
<td>1</td>
<td>s</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
### Signal Specifications

Specifications apply over all line in \( V_{IN\_EXTENDED} \), trim and load conditions, internal temperature \( T_{INT} = 25^\circ C \), unless otherwise noted. **Boldface** specifications apply over the temperature range of -40ºC < \( T_{INT} < 125^\circ C \).

#### Enable: EN

- The EN pin enables and disables the DCM converter; when held low the unit will be disabled.
- The EN pin has an internal pull-up to VCC and is referenced to the -IN pin of the converter.

<table>
<thead>
<tr>
<th>SIGNAL TYPE</th>
<th>STATE</th>
<th>ATTRIBUTE</th>
<th>SYMBOL</th>
<th>CONDITIONS / NOTES</th>
<th>MIN</th>
<th>TYP</th>
<th>MAX</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>DIGITAL INPUT</td>
<td>Any</td>
<td>EN enable threshold</td>
<td>( V_{ENABLE-EN} )</td>
<td></td>
<td></td>
<td>2.31</td>
<td></td>
<td>V</td>
</tr>
<tr>
<td></td>
<td></td>
<td>EN disable threshold</td>
<td>( V_{ENABLE-DIS} )</td>
<td></td>
<td>0.99</td>
<td></td>
<td></td>
<td>V</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Internally generated ( V_{CC} )</td>
<td>( V_{CC} )</td>
<td></td>
<td>3.21</td>
<td>3.30</td>
<td>3.39</td>
<td>V</td>
</tr>
<tr>
<td></td>
<td></td>
<td>EN Internal Pull up resistance to ( V_{CC} )</td>
<td>( R_{ENABLE-INT} )</td>
<td></td>
<td>9.5</td>
<td>10.0</td>
<td>10.5</td>
<td>kΩ</td>
</tr>
</tbody>
</table>

#### Trim: TR

- The TR pin enables and disables trim functionality when \( V_{IN} \) is applied to the DCM converter.
- When \( V_{IN} \) first crosses \( V_{IN\_UVLO+} \), the voltage on TR determines whether or not trim is active.
- If TR is not floating at power up and has a voltage less than TR trim enable threshold, trim is active.
- If trim is active, the TR pin provides dynamic trim control with at least 30Hz of -3dB control bandwidth over the output voltage of the DCM converter.
- The TR pin has an internal pull-up to VCC and is referenced to the -IN pin of the converter.

<table>
<thead>
<tr>
<th>SIGNAL TYPE</th>
<th>STATE</th>
<th>ATTRIBUTE</th>
<th>SYMBOL</th>
<th>CONDITIONS / NOTES</th>
<th>MIN</th>
<th>TYP</th>
<th>MAX</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>DIGITAL INPUT</td>
<td>Startup</td>
<td>TR trim disable threshold</td>
<td>( V_{TRIM-DIS} )</td>
<td>Trim disabled when TR above this threshold at power up</td>
<td>3.20</td>
<td></td>
<td></td>
<td>V</td>
</tr>
<tr>
<td></td>
<td></td>
<td>TR trim enable threshold</td>
<td>( V_{TRIM-EN} )</td>
<td>Trim enabled when TR below this threshold at power up</td>
<td>3.15</td>
<td></td>
<td></td>
<td>V</td>
</tr>
<tr>
<td></td>
<td>Operational with Trim enabled</td>
<td>Internally generated ( V_{CC} )</td>
<td>( V_{CC} )</td>
<td></td>
<td>3.21</td>
<td>3.30</td>
<td>3.39</td>
<td>V</td>
</tr>
<tr>
<td></td>
<td></td>
<td>TR pin analog range</td>
<td>( V_{TRIM-RANGE} )</td>
<td>Trim ( V_{OUT} ) higher than output voltage trim range ( V_{OUT_TRIMMING} ) could possibly cause output OVP</td>
<td>0</td>
<td>1.9</td>
<td>3.15</td>
<td>V</td>
</tr>
<tr>
<td></td>
<td></td>
<td>VOUT referred TR pin resolution</td>
<td>( V_{OUT_RES} )</td>
<td>With ( V_{CC} = 3.3 ) V</td>
<td>18.0</td>
<td></td>
<td></td>
<td>mV</td>
</tr>
<tr>
<td></td>
<td></td>
<td>TR internal pull up resistance to ( V_{CC} )</td>
<td>( R_{TRIM-INT} )</td>
<td></td>
<td>9.5</td>
<td>10.0</td>
<td>10.5</td>
<td>kΩ</td>
</tr>
</tbody>
</table>

#### Fault: FT

- The FT pin is a Fault flag pin.
- When the module is enabled and no fault is present, the FT pin does not have current drive capability.
- Whenever the powertrain stops (due to a fault protection or disabling the module by pulling EN low), the FT pin output Vcc and provides current to drive an external circuit.
- When module starts up, the FT pin is pulled high to \( V_{CC} \) during microcontroller initialization and will remain high until soft start process starts.

<table>
<thead>
<tr>
<th>SIGNAL TYPE</th>
<th>STATE</th>
<th>ATTRIBUTE</th>
<th>SYMBOL</th>
<th>CONDITIONS / NOTES</th>
<th>MIN</th>
<th>TYP</th>
<th>MAX</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>DIGITAL OUTPUT</td>
<td>Any</td>
<td>FT internal pull up resistance to ( V_{CC} )</td>
<td>( R_{FAULT-INT} )</td>
<td></td>
<td>474</td>
<td>499</td>
<td>525</td>
<td>kΩ</td>
</tr>
<tr>
<td></td>
<td>FT Active</td>
<td>FT Voltage</td>
<td>( V_{FAULT-ACTIVE} )</td>
<td>At rated Current drive capability</td>
<td>3.0</td>
<td></td>
<td></td>
<td>V</td>
</tr>
<tr>
<td></td>
<td></td>
<td>FT current drive capability</td>
<td>( I_{FAULT-ACTIVE} )</td>
<td>Over-current FT drive beyond its capability may cause module damage</td>
<td>4</td>
<td></td>
<td></td>
<td>mA</td>
</tr>
<tr>
<td></td>
<td></td>
<td>FT response time</td>
<td>( t_{FT-ACTIVE} )</td>
<td>Delay from cessation of switching to FT Pin Active</td>
<td>200</td>
<td></td>
<td></td>
<td>µs</td>
</tr>
</tbody>
</table>
Functional Block Diagram

Primary & Secondary Powertrains

Top Cell

Bottom Cell

Control & Monitoring

Power Limit

Modulator

Primary Based VOUT Sense

Synchronous Floating MOSFET Gate driver

Temperature

Reference and Soft Start

Powertrain Enable

Primary Based IOUT Sense

Error Amplifier

VOUT Load Regulation and ILIMIT

Fault Monitoring

OTP

Output Under Voltage

OVP

Output Short Circuit

TR

EN

FT

+VIN

–VIN

CIN-INT

COUT-INT

VCC

+OUT

–OUT

Primary & Secondary Powertrains

+IN

–IN

CIN-INT

VOUT Sense

Powertrain Enable

VOUT Load Regulation and ILIMIT

Error Amplifier

Reference and Soft Start

Fault Monitoring

OTP

Output Under Voltage

OVP

Output Short Circuit

TR

EN

FT

+VIN

–VIN

CIN-INT

COUT-INT

VCC

+OUT

–OUT

Primary & Secondary Powertrains

+IN

–IN

CIN-INT

COUT-INT

VCC

+OUT

–OUT

Primary & Secondary Powertrains

+IN

–IN

CIN-INT

COUT-INT

VCC

+OUT

–OUT
High Level Functional State Diagram

Conditions that cause state transitions are shown along arrows. Sub-sequence activities listed inside the state bubbles.

Application of $V_{IN}$

$V_{IN} > V_{IN-INIT}$

**INITIALIZATION SEQUENCE**
- $t_{INIT}$ delay
- Powertrain: Stopped
- FT = True

$V_{IN} > V_{IN-UVLO}$ and not Over-temp TR mode latched

**STANDBY**
- Powertrain: Stopped
- FT = True

**SOFT START**
- $V_{OUT}$ Ramp Up
- $t_{ss}$ delay
- EN = True and No Faults
- $t_{ON}$ delay
- EN = False
- $t_{OFF}$ delay

**RUNNING**
- Regulates $V_{OUT}$
- Powertrain: Active
- FT = False

**NON LATCHED FAULT**
- $t_{OFF}$ delay
- Fault Removed
- $t_{MIN-OFF}$ delay

**REINITIALIZATION SEQUENCE**
- $t_{INIT}$ delay
- Powertrain: Stopped
- FT = True

**NON LATCHED FAULT**
- $t_{FAULT}$ delay
- Powertrain: Stopped
- FT = True

**LATCHED FAULT**
- Powertrain: Stopped
- FT = True

$EN = False$

Fault Removed

$INPUT OVLO$ or $INPUT UVLO$

Over-temp or $OUTPUT UVP$

$INPUT OVLO$ or $INPUT UVLO$

$OUTPUT OVP$

$EN = False$

$t_{MIN-OFF}$ delay

$t_{ON}$ delay

$t_{OFF}$ delay

$t_{INIT}$ delay
Timing Diagrams

Module Inputs are shown in blue; Module Outputs are shown in brown.
Timing Diagrams (Cont.)

Module Inputs are shown in blue; Module Outputs are shown in brown.
Typical Performance Characteristics

The following figures present typical performance at $T_C = 25^\circ C$, unless otherwise noted. See associated figures for general trend data.

**Figure 1** — Electrical Specified Operating Area

**Figure 2** — Disabled power consumption vs. $V_{IN}$

**Figure 3** — No load power dissipation vs. $V_{IN}$ at nominal trim

**Figure 4** — $V_{OUT}$ vs. operating temperature trend, at full load and nominal line

**Figure 5** — $V_{OUT}$ vs. load current trend, at room temperature and nominal line

**Figure 6** — Initial startup from EN pin, with soft-start ramp. $V_{IN} = 290 \text{ V}, C_{OUT,EXT} = 10000 \mu\text{F}, R_{LOAD} = 0.317 \Omega$
Typical Performance Characteristics (cont.)

The following figures present typical performance at $T_C = 25^\circ$C, unless otherwise noted. See associated figures for general trend data.

**Figure 7** — Full Load Efficiency vs. $V_{IN}$, $V_{OUT} = 11.5$ V

**Figure 8** — Full Load Efficiency vs. $V_{IN}$, $V_{OUT} = 13.8$ V

**Figure 9** — Full Load Efficiency vs. $V_{IN}$, $V_{OUT} = 15.5$ V

**Figure 10** — $V_{IN}$ to $V_{OUT}$ efficiency and power dissipation vs. $I_{OUT}$, $T_{CASE} = -40^\circ$C

**Figure 11** — $V_{IN}$ to $V_{OUT}$ efficiency and power dissipation vs. $I_{OUT}$, $T_{CASE} = 25^\circ$C

**Figure 12** — $V_{IN}$ to $V_{OUT}$ efficiency and power dissipation vs. $I_{OUT}$, $T_{CASE} = 90^\circ$C
Typical Performance Characteristics (cont.)

The following figures present typical performance at $T_C = 25^\circ C$, unless otherwise noted. See associated figures for general trend data.

**Figure 13** — 10% to 100% load transient response, $V_{in} = 290 V$, nominal trim, $C_{OUT,EXT} = 1000 \mu F$

**Figure 14** — Powertrain switching frequency vs. load, at nominal trim

**Figure 15** — Effective internal input capacitance vs. applied voltage

**Figure 16** — 100% to 10% load transient response, $V_{in} = 290 V$, nominal trim, $C_{OUT,EXT} = 1000 \mu F$

**Figure 17** — Powertrain switching frequency vs. load, at nominal $V_{in}$

**Figure 18** — Typical output voltage ripple, $V_{IN} = 290 V$, $V_{OUT} = 13.8 V$, $C_{OUT,EXT} = 1000 \mu F$, $R_{LOAD} = 0.317 \Omega$
General Characteristics
Specifications apply over all line in \( V_{IN-EXTENDED} \), trim and load conditions, internal temperature \( T_{INT} = 25^\circ C \), unless otherwise noted. **Boldface** specifications apply over the temperature range of \(-40^\circ C < T_{INT} < 125^\circ C\).

<table>
<thead>
<tr>
<th>Attribute</th>
<th>Symbol</th>
<th>Conditions / Notes</th>
<th>Min</th>
<th>Typ</th>
<th>Max</th>
<th>Unit</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Mechanical</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Length</td>
<td>L</td>
<td></td>
<td>47.5/1.871</td>
<td>47.9/1.886</td>
<td>48.3/1.901</td>
<td>mm/in</td>
</tr>
<tr>
<td>Width</td>
<td>W</td>
<td></td>
<td>22.6/0.893</td>
<td>22.8/0.898</td>
<td>22.9/0.903</td>
<td>mm/in</td>
</tr>
<tr>
<td>Height</td>
<td>H</td>
<td></td>
<td>7.2/0.284</td>
<td>7.26/0.286</td>
<td>7.31/0.288</td>
<td>mm/in</td>
</tr>
<tr>
<td>Volume</td>
<td>Vol</td>
<td>No heat sink</td>
<td>7.90/0.48</td>
<td></td>
<td></td>
<td>cm³/in³</td>
</tr>
<tr>
<td>Weight</td>
<td>W</td>
<td></td>
<td>29.2/1.03</td>
<td></td>
<td></td>
<td>g/oz</td>
</tr>
<tr>
<td>Lead finish</td>
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<td></td>
<td></td>
<td></td>
<td>µm</td>
</tr>
<tr>
<td>Nickel</td>
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<td>2.03</td>
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<tr>
<td>Palladium</td>
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<td>0.02</td>
<td>0.15</td>
<td></td>
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<tr>
<td>Gold</td>
<td></td>
<td></td>
<td>0.003</td>
<td>0.05</td>
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</tr>
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<td><strong>Thermal</strong></td>
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<td></td>
<td></td>
<td></td>
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</tr>
<tr>
<td>Operating internal temperature</td>
<td>( T_{INT} )</td>
<td>Estimated thermal resistance to maximum temperature internal component from isothermal top</td>
<td>-40</td>
<td>125</td>
<td>°C</td>
<td></td>
</tr>
<tr>
<td>Thermal resistance top side</td>
<td>( \Phi_{INT-TOP} )</td>
<td>Estimated thermal resistance to maximum temperature internal component from isothermal top</td>
<td>1.80</td>
<td>5.54</td>
<td>°C/W</td>
<td></td>
</tr>
<tr>
<td>Thermal resistance leads</td>
<td>( \Phi_{INT-LEADS} )</td>
<td>Estimated thermal resistance to maximum temperature internal component from isothermal leads</td>
<td></td>
<td>1.58</td>
<td>°C/W</td>
<td></td>
</tr>
<tr>
<td>Thermal resistance bottom side</td>
<td>( \Phi_{INT-BOTTOM} )</td>
<td>Estimated thermal resistance to maximum temperature internal component from isothermal bottom</td>
<td></td>
<td></td>
<td>°C/W</td>
<td></td>
</tr>
<tr>
<td>Thermal capacity</td>
<td></td>
<td></td>
<td>21</td>
<td></td>
<td>Ws/°C</td>
<td></td>
</tr>
<tr>
<td><strong>Assembly</strong></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Storage temperature</td>
<td>( T_{ST} )</td>
<td>Method per Human Body Model Test ESDA/JEDEC JDS-001-2012</td>
<td>-40</td>
<td>125</td>
<td>°C</td>
<td></td>
</tr>
<tr>
<td>ESD rating</td>
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<td>CLASS 1C</td>
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<td>HBM</td>
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<tr>
<td>CDM</td>
<td></td>
<td></td>
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<td></td>
</tr>
<tr>
<td><strong>Soldering(^1)</strong></td>
<td></td>
<td></td>
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<td></td>
</tr>
<tr>
<td>Peak temperature top case</td>
<td></td>
<td>For further information, please contact factory applications</td>
<td></td>
<td>135</td>
<td>°C</td>
<td></td>
</tr>
</tbody>
</table>

\(^1\) Product is not intended for reflow solder attach.
**General Characteristics (Cont.)**

Specifications apply over all line in VIN-EXTENDED, trim and load conditions, internal temperature $T_{INT} = 25^\circ C$, unless otherwise noted. **Boldface** specifications apply over the temperature range of $-40^\circ C < T_{INT} < 125^\circ C$.

<table>
<thead>
<tr>
<th>Attribute</th>
<th>Symbol</th>
<th>Conditions / Notes</th>
<th>Min</th>
<th>Typ</th>
<th>Max</th>
<th>Unit</th>
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</thead>
<tbody>
<tr>
<td>Safety</td>
<td>V_{HIPOT}</td>
<td>IN to OUT</td>
<td>4242</td>
<td>Vdc</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>IN to CASE</td>
<td>2121</td>
<td>Vdc</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>OUT to CASE</td>
<td>2121</td>
<td>Vdc</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Reliability</td>
<td>MTBF</td>
<td>MIL-HDBK-217 Plus Parts Count - 25°C Ground Benign, Stationary, Indoors / Computer</td>
<td>1.85</td>
<td>Mhrs</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>Telcordia Issue 2, Method I Case 3, 25°C, 100% D.C., GB, GC</td>
<td>2.35</td>
<td>Mhrs</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Agency Approvals</td>
<td></td>
<td>cTÜVus; EN 60950-1</td>
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<td>cURus, 60950-1</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

CE Marked for Low Voltage Directive and RoHS Recast Directive as Applicable.
Pin Functions

**+IN, -IN**
Input power pins. -IN is the reference for all control pins, and therefore a Kelvin connection is recommended as close as possible to the pin on the package, to reduce effects of voltage drop due to -IN currents.

**+OUT, -OUT**
Output power pins.

**EN (Enable)**
This pin enables and disables the DCM converter; when held low the unit will be disabled. It is referenced to the -IN pin of the converter. The EN pin has an internal pull-up to Vcc through a 10 kΩ resistor.

- **Output enable:** When EN is allowed to pull up above the enable threshold, the module will be enabled. If leaving EN floating, it is pulled up to Vcc and the module will be enabled.
- **Output disable:** EN may be pulled down externally in order to disable the module.
- **EN is an input only,** it does not pull low in the event of a fault.
- **The EN pins of multiple units should be driven high concurrently to permit the array to start in to maximum rated load. However, the direct interconnection of multiple EN pins requires additional considerations, as discussed in the section on Array Operation.**

**TR (Trim)**
The TR pin is used to select the trim mode and to trim the output voltage of the DCM converter. The TR pin has an internal pull-up to Vcc through a 10 kΩ resistor.

The DCM will latch trim behavior at application of V_{IN}, and persist in that same behavior until loss of input voltage.

- **At application of V_{IN}, if TR is sampled at above V_{TRIM-DIS}, the module will latch in a non-trim mode, and will ignore the TR input for as long as V_{IN} is present.**
- **At application of V_{IN}, if TR is sampled at below V_{TRIM-EN}, the TR will serve as an input to control real time output voltage trim. It will persist in this behavior until V_{IN} is no longer present.**

If trim is active when the DCM is operating, the TR pin provides dynamic trim control at a typical 30 Hz of -3dB bandwidth over the output voltage.

**FT (Fault)**
The FT pin provides a Fault signal.

Anytime the module is enabled and has not recognized a fault, the FT pin is inactive. FT has an internal 499 kΩ pull-up to Vcc, therefore a shunt resistor, R_{SHUNT}, of approximately 50 kΩ can be used to ensure the LED is completely off when there is no fault, per the diagram below.

Whenever the powertrain stops (due to a fault protection or disabling the module by pulling EN low), the FT pin becomes active and provides current to drive an external circuit.

When active, FT pin drives to Vcc with up to 4 mA of external loading. Module may be damaged from an over-current FT drive, thus a resistor in series for current limiting is recommended.

The FT pin becomes active momentarily when the module starts up.

Typical External Circuits for Signal Pins (TR, EN, FT)

![Typical External Circuits for Signal Pins (TR, EN, FT)](image-url)
Module performance is guaranteed through output voltage trim range $V_{OUT-TRIMMING}$. If $V_{OUT}$ is trimmed higher than that range, then certain combinations of line and load transient conditions may trigger the output OVP.

**Nominal Output Voltage Load Line**
Throughout this document, the programmed output voltage, (either the specified nominal output voltage if trim is inactive) or the trimmed output voltage if trim is active, is specified at full load, and at room temperature. The actual output voltage of the DCM is given by the programmed output voltage, with modification based on load and temperature. The nominal output voltage is 13.8 V, and the actual output voltage will match this at full load and room temperature with trim inactive.

The largest modification to the actual output voltage compared to the programmed output is due to a 5.263% $V_{OUT-NOM}$ load line, which for this model corresponds to $\Delta V_{OUT-LOAD}$ of 0.73 V. As the load is reduced, the internal error amplifier reference, and by extension the output voltage, rises in response. This load line is the primary enabler of the wireless current sharing amongst an array of DCMs. The load line impact on the output voltage is absolute, and is not scaled by the trim voltage.

Furthermore, when the load current is below 5% of the rated capacity, there is an additional $\Delta V$ added to the output voltage, which is related to Burst Mode. Please see the section on Burst Mode below for details.

For a given programmed output voltage, the actual output voltage versus load current at for nominal trim, nominal line, and room temperature is above 5% load given by the following equation:

$$V_{OUT} = 13.8 + 0.73 - 0.73 \times I_{OUT} / 43.5 \quad (2)$$

**Nominal Output Voltage Temperature Coefficient**
There is an additional additive term to the programmed output voltage, which is based on the temperature of the module. This term permits improved thermal balancing among modules in an array, especially when the factory nominal trim point is utilized (trim mode inactive). This term is much smaller than the load line described above, representing only a 0.138 V change every 75°C over the entire rated temperature range. Regulation coefficient is relative to 25°C $T_{INT}$ (hottest internal temperature).

For nominal trim, nominal line, and full load, the output voltage relates to the temperature according to the following equation:

$$V_{OUT} = 13.8 - 0.138 \times (T_{INT} - 25)/75 \quad (3)$$

where $T_{INT}$ is in °C.

The impact of temperature coefficient on the output voltage is absolute, and does not scale with trim or load.

---

**Design Guidelines**

**Building Blocks and System Design**
The DCM™ converter input accepts the full 160 to 420 V range, and it generates an isolated trimmable 13.8 Vdc output. Multiple DCMs may be paralleled for higher power capacity via wireless load sharing, even when they are operating off of different input voltage supplies.

The DCM converter provides a regulated output voltage around the defined nominal load line and temperature coefficients. The load line and temperature coefficients enable configuration of an array of DCM converters which manage the output load with no share bus among modules. Downstream regulators may be used to provide tighter voltage regulation, if required.

The DCM290P138T600A40 may be used in standalone applications where the output power requirements are up to 600 W. However, it is easily deployed as arrays of modules to increase power handling capacity. Arrays of up to eight units have been qualified for 4800 W capacity. Application of DCM converters in an array requires no derating of the maximum available power versus what is specified for a single module.

**Soft Start**
When the DCM starts, it will go through a soft start sequence. Notice the module will only startup if the input voltage is within the range of $V_{IN}$. After startup, Module can then operate in the wider input voltage range $V_{IN EXTENDED}$.

The soft start sequence ramps the output voltage by modulating the internal error amplifier reference. This causes the output voltage to approximate a piecewise linear ramp. The output ramp finishes when the voltage reaches either the nominal output voltage, or the approximate a piecewise linear ramp. The output ramp finishes after the unit self-protects from a fault condition, the trim mode is inactive). This term is much smaller than the load line described above, representing only a 0.138 V change every 75°C over the entire rated temperature range. Regulation coefficient is relative to 25°C $T_{INT}$ (hottest internal temperature).

For nominal trim, nominal line, and full load, the output voltage relates to the temperature according to the following equation:

$$V_{OUT} = 13.8 + 0.73 - 0.73 \times I_{OUT} / 43.5 \quad (2)$$

**Trim Mode and Output Trim Control**
When the input voltage is initially applied to a DCM, and after $T_{INIT}$ elapses, the trim pin voltage $V_{TR}$ is sampled. The TR pin has an internal pull up resistor to $V_{CC}$, so unless external circuitry pulls the pin voltage lower, it will pull up to $V_{CC}$. If the initially sampled trim pin voltage is higher than $V_{TRM-DIS}$, then the DCM will disable trimming as long as the $V_{IN}$ remains applied. In this case, for all subsequent operation the output voltage will be programmed to the nominal. This minimizes the support components required for applications that only require the nominal rated Vout, and also provides the best output setpoint accuracy, as there are no additional errors from external trim components.

If at initial application of $V_{IN}$, the TR pin voltage is prevented from exceeding $V_{TRM-EN}$, then the DCM will activate trim mode, and it will remain active for as long as $V_{IN}$ is applied.

$V_{OUT}$ set point under full load and room temperature can be calculated using the equation below:

$$V_{OUT} = 10.00 + (6.48 \times V_{TR}/V_{CC}) \quad (1)$$

Note that while the soft-start routine described above does re-arm after the unit self-protects from a fault condition, the trim mode is not changed when a DCM recovers from any fault condition or being disabled.

If $V_{TR}$ is driven above the point where the trimmed Vout reaches the maximum trimmed Vout range, then the $V_{OUT}$ will hold at the maximum of the trim range, and not wrap around or return to nominal $V_{OUT}$.
Overall Output Voltage Transfer Function

Taking trim (equation 1), load line (equation 2) and temperature coefficient (equation 3) into account, the general equation relating the DC VOUT at nominal line to programmed trim (when active), load, and temperature is given by:

\[
V_{OUT} = 10.00 + (6.48 \cdot \frac{V_{tr}}{V_{CC}}) + 0.73 + \Delta V - 0.73 \\
\cdot \frac{I_{OUT}}{43.5} - 0.138 \cdot \frac{(T_{INT} - 25)}{75}
\] (4)

Use 0 V for \(\Delta V\) when load is from 5% to 100% load, and up to 2.3 V when operating at <5% load. See section on Burst Mode operation for light load effects on output voltage.

Output Current Limit

The DCM features a fully operational current limit which effectively keeps the module operating inside the Safe Operating Area (SOA) for all valid trim and load profiles. The current limit approximates a “brick wall” limit, where the output current is prevented from exceeding the current limit threshold by reducing the output voltage via the internal error amplifier reference. The current limit threshold at nominal trim and below is typically 105% of maximum output current, but can vary from 100% to 117% of maximum output current. In order to preserve the SOA, in cases where the converter is trimmed above the nominal output voltage, the current limit threshold is automatically reduced to limit the available output power.

When the output current exceeds the current limit threshold, current limit action is held off by 1ms, which permits the DCM to momentarily deliver higher peak output currents to the load. Peak output power during this time is still constrained by the internal Power Limit of the module. The fast Power Limit and relatively slow Current Limit work together to keep the module inside the SOA. Delaying entry into current limit also permits the DCM to minimize droop voltage for load steps.

Sustained operation in current limit is permitted, and no derating of output power is required, even in an array configuration.

Some applications may benefit from well matched current distribution, in which case fine tuning sharing via the trim pins permits control over sharing. The DCM does not require this for proper operation, due to the power limit and current limit behaviors described here.

Current limit can reduce the output voltage to as little as the UVP threshold (\(V_{OUT-UVP}\)). Below this minimum output voltage compliance level, further loading will cause the module to shut down due to the output undervoltage fault protection.

Line Impedance, Input Slew rate and Output Stability Requirements

Connect a high-quality, low-noise power supply to the +IN and –IN terminals. An external capacitance of 0.68uF is required. Additional capacitance may have to be added between +IN and –IN to make up for impedances in the interconnect cables as well as deficiencies in the source.

Significant source impedance can bring system stability issue for a regulated DC-DC converter and needs to be avoided or compensated. Additional information can be found in the filter design application note: www.vicorpower.com/documents/application_notes/vichip_appnote23.pdf

Please refer to this input filter design tool to ensure input stability: http://app2.vicorpower.com/filterDesign/intiFilter.do

Ensure that the input voltage slew rate is less than 1V/us, otherwise a pre-charge circuit is required for the DCM input to control the input voltage slew rate and prevent overstress to input stage components. For the DCM, output voltage stability is guaranteed as long as hold up capacitance \(C_{OUT-EXE}\) falls within the specified ranges.

Input Fuse Selection

DCM is not internally fused in order to provide flexibility in configuring power systems. Input line fusing is recommended at system level, in order to provide thermal protection in case of catastrophic failure. The fuse shall be selected by closely matching system requirements with the following characteristics:

- Current rating (usually greater than the DCM converter’s maximum current)
- Maximum voltage rating (usually greater than the maximum possible input voltage)
- Ambient temperature
- Breaking capacity per application requirements
- Nominal melting \(I_t\)
- Recommended fuse: 5A Bussmann PC-Tron

(see agency approval for additional fuses)

Fault Handling

Input Undervoltage Fault Protection (UVLO)

The converter’s input voltage is monitored to detect an input under voltage condition. If the converter is not already running, then it will ignore enable commands until the input voltage is greater than \(V_{IN-UVLO}\). If the converter is running and the input voltage falls below \(V_{IN-UVLO}\), the converter recognizes a fault condition, the powertrain stops switching, and the output voltage of the unit falls.

Input voltage transients which fall below UVLO for less than \(t_{UVLO}\) may not be detected by the fault protection logic, in which case the converter will continue regular operation. No protection is required in this case.

Once the UVLO fault is detected by the fault protection logic, the converter shuts down and waits for the input voltage to rise above \(V_{IN-UVLO}\). Provided the converter is still enabled, it will then restart.

Input Overvoltage Fault Protection (OVLO)

The converter’s input voltage is monitored to detect an input over voltage condition. When the input voltage is more than the \(V_{IN-OVLO}\), a fault is detected, the powertrain stops switching, and the output voltage of the converter falls.

After an OVLO fault occurs, the converter will wait for the input voltage to fall below \(V_{IN-OVLO}\). Provided the converter is still enabled, the powertrain will restart.

The powertrain controller itself also monitors the input voltage. Transient OVLO events which have not yet been detected by the fault sequence logic may first be detected by the controller if the input slew rate is sufficiently large. In this case, powertrain switching will immediately stop. If the input voltage falls back in range before the fault sequence logic detects the out of range condition, the powertrain will resume switching and the fault logic will not interrupt operation. Regardless of whether the powertrain is running at the time or not, if the input voltage does not recover from OVLO before \(t_{OVLO}\), the converter fault logic will detect the fault.

Output Undervoltage Fault Protection (UVP)

The converter determines that an output overload or short circuit condition exists by measuring its primary sensed output voltage and...
the output of the internal error amplifier. In general, whenever the powertrain is switching and the primary-sensed output voltage falls below $V_{OUT-UVF}$ threshold, a short circuit fault will be registered. Once an output undervoltage condition is detected, the powertrain immediately stops switching, and the output voltage of the converter falls. The converter remains disabled for a time $t_{FAULT}$. Once recovered and provided the converter is still enabled, the powertrain will again enter the soft start sequence after $t_{INIT}$ and $t_{ON}$.

Temperature Fault Protections (OTP)
The fault logic monitors the internal temperature of the converter. If the measured temperature exceeds $T_{INT-OTP}$, a temperature fault is registered. As with the under voltage fault protection, once a temperature fault is registered, the powertrain immediately stops switching, the output voltage of the converter falls, and the converter remains disabled for at least time $t_{FAULT}$. Then, the converter waits for the internal temperature to return to below $T_{INT-OTP}$ before recovering. Provided the converter is still enabled, the DCM will restart after $t_{INIT}$ and $t_{ON}$.

Output Overvoltage Fault Protection (OVP)
The converter monitors the output voltage during each switching cycle by a corresponding voltage reflected to the primary side control circuitry. If the primary sensed output voltage exceeds $V_{OUT-OVF}$ the OVP fault protection is triggered. The control logic disables the powertrain, and the output voltage of the converter falls. This type of fault is latched, and the converter will not start again until the latch is cleared. Clearing the fault latch is achieved by either disabling the converter via the EN pin, or else by removing the input power such that the input voltage falls below $V_{IN-INT}$.

External Output Capacitance
The DCM converter compensation requires a minimal external capacitor on the output for proper operation and for good transient load regulation. An external capacitor of 1000 uF to 10,000 uF per DCM is required with ESR of 10 mΩ or greater.

Burst Mode
Under light load conditions, the DCM converter may operate in burst mode depending on the line voltage. Burst mode occurs whenever the internal power consumption of the converter combined with the external output load is less than the maximum power transfer per switching cycle. To prevent the output voltage from rising in this case, the powertrain is switched off and on repeatedly, to effectively lower the average switching frequency, and permit operation with no external load. During the time when the power train is off, the module internal consumption is significantly reduced, and so there is a notable reduction in no-load input power in burst mode. When the load is less than 5% of rated Iout, the output voltage may rise by a maximum of 2.3 V, above the output voltage calculated from trim, temperature, and load-line conditions.

Thermal Design
Based on the safe thermal operating area shown in page 5, the full rated power of the DCM290P138T600A40 can be processed provided that the top, bottom, and leads are all held below 80°C. These curves highlight the benefits of dual sided thermal management, but also demonstrate the flexibility of the Vicor ChiP platform for customers who are limited to cooling only the top or the bottom surface.

The OTP sensor is located on the top side of the internal PCB structure. Therefore in order to ensure effective over-temperature fault protection, the case bottom temperature must be constrained by the thermal solution such that it does not exceed the temperature of the case top.

The ChiP package provides a high degree of flexibility in that it presents three pathways to remove heat from internal power dissipating components. Heat may be removed from the top surface, the bottom surface and the leads. The extent to which these three surfaces are cooled is a key component for determining the maximum power that is available from a ChiP, as can be seen from Figure 19.

Since the ChiP has a maximum internal temperature rating, it is necessary to estimate this internal temperature based on a real thermal solution. Given that there are three pathways to remove heat from the ChiP, it is helpful to simplify the thermal solution into a roughly equivalent circuit where power dissipation is modeled as a current source, isothermal surface temperatures are represented as voltage sources and the thermal resistances are represented as resistors. Figure 19 shows the “thermal circuit” for a 4623 ChiP DCM in an application where the top, bottom, and leads are cooled. In this case, the DCM power dissipation is $P_{TOTAL}$ and the three surface temperatures are represented as $T_{CASE\_TOP}$, $T_{CASE\_BOTTOM}$, and $T_{LEADS}$. This thermal system can now be very easily analyzed with simple resistors, voltage sources, and a current source.

This analysis provides an estimate of heat flow through the various pathways as well as internal temperature.

![Figure 19 — Double side cooling and leads thermal model](image)

Alternatively, equations can be written around this circuit and analyzed algebraically:

$$T_{INT} - PD_1 \cdot \Phi_{INT-TOP} = T_{CASE\_TOP}$$
$$T_{INT} - PD_2 \cdot \Phi_{INT-BOTTOM} = T_{CASE\_BOTTOM}$$
$$T_{INT} - PD_3 \cdot \Phi_{INT-LEADS} = T_{LEADS}$$
$$PD_{TOTAL} = PD_1 + PD_2 + PD_3$$

Where $T_{INT}$ represents the internal temperature and $PD_1$, $PD_2$, and $PD_3$ represent the heat flow through the top side, bottom side, and leads respectively.

![Figure 20 — One side cooling and leads thermal model](image)
Figure 20 shows a scenario where there is no bottom side cooling. In this case, the heat flow path to the bottom is left open and the equations now simplify to:

\[
T_{INT} - PD_1 \cdot \Phi_{INT-TOP} = T_{CASE\_TOP} \\
T_{INT} - PD_3 \cdot \Phi_{INT\_LEADS} = T_{LEADS} \\
PD_{TOTAL} = PD_1 + PD_3
\]

Figure 21 shows a scenario where there is no bottom side and leads cooling. In this case, the heat flow path to the bottom is left open and the equations now simplify to:

\[
T_{INT} - PD_1 \cdot \Phi_{INT-TOP} = T_{CASE\_TOP} \\
PD_{TOTAL} = PD_1
\]

Vicor provides a suite of online tools, including a simulator and thermal estimator which greatly simplify the task of determining whether or not a DCM thermal configuration is sufficient for a given condition. These tools can be found at: www.vicorpower.com/powerbench.

Array Operation

A decoupling network is needed to facilitate paralleling:

- An output inductor should be added to each DCM, before the outputs are bussed together to provide decoupling.
- Each DCM needs a separate input filter, even if the multiple DCMs share the same input voltage source. These filters limit the ripple current reflected from each DCM, and also help suppress generation of heat frequency currents that can result when multiple powertrains input stages are permitted to directly interact.

If signal pins (TR, EN, FT) are not used, they can be left floating, and DCM will work in the nominal output condition.

When common mode noise in the input side is not a concern, TR and EN can be driven and FT received using the –IN as a reference.

An example of DCM paralleling circuit is shown in Figure 22.

Recommended values to start with:

- **L1**: L1 = 1 uH, minimized DCR;
- **R1**: 1 Ohm;
- **C1**: Ceramic capacitors in parallel, C1 = 2 uF;
- **L2**: L2 ≥ 0.15 uH;
- **C3**: electrolytic or tantalum capacitor, 1000 uF ≤ C3 ≤ 10000 uF;
- **C4, C5**: additional ceramic/electrolytic capacitors, if needed for output ripple filtering;

**R3**: current limit resistor for fault pin, a resistor of at least 1 k is recommended;

In order to help sensitive signal circuits reject potential noise, additional components are recommended:

- **R2**: 301 Ohm, facilitate noise attenuation for TR pin;
- **FB1, C2**: FB1 is a ferrite bead with an impedance of at least 10 Ω at 100MHz. C2 can be a ceramic capacitor of 0.1uF. Facilitate noise attenuation for EN pin.

When common mode noise rejection in the input side is needed, common modes choke can be added in the input side of each DCM. An example of DCM paralleling circuit is shown below:

Notice that each group of control pins need to be individually driven and isolated from the other groups control pins. This is because -IN of each DCM can be at a different voltage due to the common mode chokes. Attempting to share control pin circuitry could lead to incorrect behavior of the DCMs.
An array of DCMs used at the full array rated power may generally have one or more DCMs operating at current limit, due to sharing errors. Load sharing is functionally managed by the load line. Thermal balancing is improved by the nominal effective temperature coefficient of the output voltage setpoint.

DCMs in current limit will operate with higher output current or power than the rated levels. Therefore the following Thermal Safe Operating Area plot should be used for array use, or loads that drive the DCM in to current limit for sustained operation. Top side only cooling is not recommended for array or current limit operation.

**Figure 24 — Maximum Power Dissipation for Array or Current Limit Operation**
DCM Module Product Outline Drawing Recommended PCB Footprint and Pinout

**TOP VIEW (COMPONENT SIDE)**

**BOTTOM VIEW**

**RECOMMENDED HOLE PATTERN (COMPONENT SIDE)**

**NOTES:**
1. RoHS COMPLIANT PER CST-0001 LATEST REVISION.
Recommended PCB Footprint for 4623 DCM with Top-side or Dual Heatsink

6123 AND 4623
RECOMMENDED LAND PATTERN
(NO GROUNDING CLIPS)
TOP SIDE SHOWN
APPLIES TO BOTH THRU HOLE
AND SURFACE MOUNT DEVICES

THRU HOLE
SEE NOTE 1

CHIP OUTLINE

6123 AND 4623
RECOMMENDED LAND PATTERN
(GROUNDING CLIPS)
TOP SIDE SHOWN
APPLIES TO BOTH THRU HOLE
AND SURFACE MOUNT DEVICES

CHIP OUTLINE

NOTES:
1. MAINTAIN 3.00 (1.181) ZIA, KEEP OUT ZONE
   0.50 (0.020) CLEAR OF ALL PCB FEATURES
2. RIVETS COMPLIANT PER CT-0001, LATEST REVISION
3. UNLESS OTHERWISE SPECIFIED, DIMENSIONS ARE MM (INCH)
   TOLERANCES ARE:
   K, K1 (0.0001) = 0, 1 (0.05)
   AZ, AX, (0.0001) = 0.003 (0.005)
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