



Pre-Regulator Module



Size:  
1.91 x 1.09 x 0.37 in  
48,6 x 27,7 x 9,5 mm

Features

- -55°C to 100°C baseplate operation
- Vin range: 16 – 50 Vdc
- Factorized Power
- High density: up to 156 W/in<sup>3</sup>
- Small footprint: 2.08 in<sup>2</sup>
- Height above board: 0.37 in (9.5 mm)
- Low weight: 1.07 oz (30.3g)
- ZVS buck-boost regulator
- Typical efficiency: 95%
- 1.3 MHz switching frequency
- Low noise operation
- Architectural flexibility

Product Overview

The VI Brick<sup>®</sup> Pre-Regulator Module is a very efficient non-isolated regulator capable of both boosting and bucking a wide range input voltage. It is specifically designed to provide a controlled Factorized Bus distribution voltage for powering downstream VI Brick Current Multiplier Modules — fast, efficient, isolated, low noise Point-of-Load (POL) converters. In combination, VI Brick PRMs and VTMs<sup>™</sup> form a complete DC-DC converter subsystem offering all of the unique benefits of Vicor's Factorized Power Architecture (FPA): high density and efficiency; low noise operation; architectural flexibility;

extremely fast transient response; and elimination of bulk capacitance at the Point-of-Load (POL).

In FPA systems, the POL voltage is the product of the Factorized Bus voltage delivered by the VI Brick PRM and the "K-factor" (the fixed voltage transformation ratio) of a downstream VTMs. The PRM controls the Factorized Bus voltage to provide regulation at the POL. Because VTMs perform true voltage division and current multiplication, the Factorized Bus voltage may be set to a value that is substantially higher than the bus voltages typically found in "intermediate bus" systems,

reducing distribution losses and enabling use of narrower distribution bus traces. A Military COTS VI Brick PRM-VTM chip set can provide up to 100 A or 120 W at a FPA system power density of 156 W/in<sup>3</sup>.

The Military COTS VI Brick PRM described in this data sheet features a unique "Adaptive Loop" compensation feedback: a single wire alternative to traditional remote sensing and feedback loops that enables precise control of an isolated POL voltage without the need for either a direct connection to the load or for noise sensitive, bandwidth limiting, isolation devices in the feedback path.

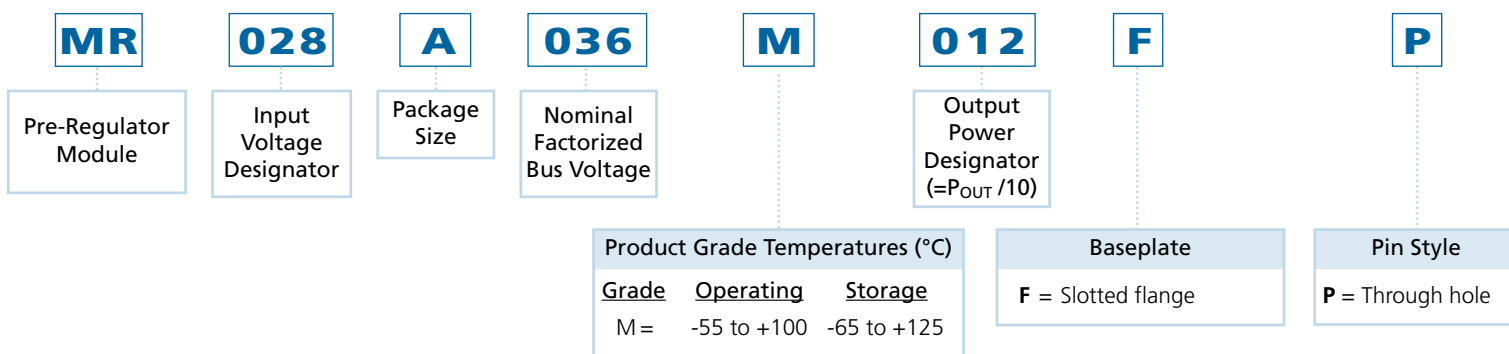
Absolute Maximum Ratings

Parameter	Values	Unit	Notes
+In to -In	-1.0 to 60.0	Vdc	
PC to -In	-0.3 to 6.0	Vdc	
PR to -In	-0.3 to 9.0	Vdc	
IL to -In	-0.3 to 6.0	Vdc	
VC to -In	-0.3 to 18.0	Vdc	
+Out to -Out	-0.3 to 59	Vdc	
SC to -Out	-0.3 to 3.0	Vdc	
VH to -Out	-0.3 to 9.5	Vdc	
OS to -Out	-0.3 to 9.0	Vdc	
CD to -Out	-0.3 to 9.0	Vdc	
SG to -Out	100	mA	
Continuous output current	3.3	Adc	
Continuous output power	120	W	
Operating temperature	-55 to +100	°C	M-Grade; baseplate
Storage temperature	-65 to +125	°C	M-Grade

**Note:** Stresses in excess of the maximum ratings can cause permanent damage to the device. Operation of the device is not implied at these or any other conditions in excess of those given in the specification. Exposure to absolute maximum ratings can adversely affect device reliability.

## SPECIFICATIONS

## PART NUMBERING

Input Specifications (Conditions are at 28 V<sub>in</sub>, 36 V<sub>f</sub><sup>[a]</sup>, full load, and 25°C ambient unless otherwise specified)

Parameter	Min	Typ	Max	Unit	Notes
Input voltage range	16.1 <sup>[b]</sup>	28	50	Vdc	
Input dV/dt			1	V/μs	
Input undervoltage turn-on		15.9	16.1	Vdc	Increases linearly to 17 V max at 100°C
Input undervoltage turn-off	12.2	13.5		Vdc	
Input overvoltage turn-on	50.5	52.5		Vdc	
Input overvoltage turn-off		53.5	55.0	Vdc	
Input quiescent current		0.5	1	mA	PC low
Input current		4.5		Adc	
Input reflected ripple current		240		mA p-p	See Figures 3 & 4
No load power dissipation		2.75	5.8	W	
Internal input capacitance		5		μF	Ceramic
Recommended external input capacitance		1,000		μF	See Figure 4 for input filter circuit. Source impedance dependent

<sup>[a]</sup> V<sub>f</sub> is factorized bus voltage (see Figure 15).

<sup>[b]</sup> Will operate down to 13.5 V after start up ≥ 16 V.

Output Specifications (Conditions are at 28 V<sub>in</sub>, 36 V<sub>f</sub><sup>[a]</sup>, full load, and 25°C baseplate unless otherwise specified)

Parameter	Min	Typ	Max	Unit	Note
Output voltage range	26	36	50	Vdc	Factorized Bus voltage (V <sub>f</sub> ) set by R <sub>OS</sub>
Output power	0		120	W	
Output current	0		3.33	Adc	
DC current limit	3.5	3.9	4.4	Adc	I <sub>L</sub> pin floating
Average short circuit current		0.125	1.25	A	Auto recovery
Set point accuracy		1.5		%	
Line regulation		0.1	0.2	%	Low line to high line
Load regulation		0.1	0.2	%	No CD resistor
Load regulation (at VTM output)		1.0	2.0	%	Adaptive Loop
Current share accuracy		5	10	%	
Efficiency					
Full load	94	95.6		%	See Figure 5,6 & 7
Output overvoltage set point	56		59.4	Vdc	
Output ripple voltage					
No external bypass		1.8	2.7	%	Factorized Bus, see Figure 12
With 10 μF capacitor		0.6	0.9	%	Factorized Bus, See Figure 13
Switching frequency	1.2	1.3	1.45	MHz	Fixed frequency - across entire operating range
Output turn-on delay					
From application of power		94	144	ms	See Figure 1
From PC pin high		100		μs	See Figure 2
Internal output capacitance		5		μF	Ceramic
Factorized Bus capacitance			47	μF	

## SPECIFICATIONS

**Environmental Qualifications****Vibration**

MIL-STD-810F method 514.5, procedure I, category 14, sine and random vibration for helicopter AH-6J main rotor with an overall level of 5.6grms, 4 hours per axis.

JESD22-B103, Condition B, 2-500Hz 3.10Grms, 30 Min

**Shock**

MIL-STD-810F method 516.5, Procedure I, 40 g, 15-23 ms saw tooth, 3 +/- shocks per axis, 18 total.

MIL-STD-810F method 516.5, Crash Hazard, Procedure V, 75g, 8-13 ms saw tooth, 3 +/- shocks per axis, 18 total.

JESD22-B104, Condition C 100G.s 2MS 5 shocks in each of 2 directions of 3 orthogonal axes (minimum total of 30 shocks).

**Acceleration**

MIL-STD 810F method 513.5 procedure I, 2-7 g (table 513.5 II Helicopter) 6 directions.

**Salt Atmosphere**

MIL-STD-810F Method 509.4 – 48 hr exposure.

**Fungus**

MIL-STD-810F Method 508.5

**Terminal Strength**

MIL-STD-202G, Method 211A, Test Condition A

**Resistance to Solvents**

MIL-STD-202G, Method 215K.

**Temperature Humidity Bias (THB)**

85°C / 85% RH Bias applied (500 hrs. minimum).

**High Temperature Operating Life (HTOL)**

JESD22-A-108-B Nom Line Full Load 1000 hrs – Product maintained at maximum operating temperature outlined in published specifications (100°C).

**Temp Cycle**

JESD22-A104B -40°C to 125°C (max temperatures dictated by max and min storage specifications outlined in product published specifications),

500 cycles – Max ramp rate 15°C / minute, 8°C / min Nominal. Product tested every 250 cycles.

SPECIFICATIONS (CONT.)

INPUT WAVEFORMS & TEST CIRCUIT

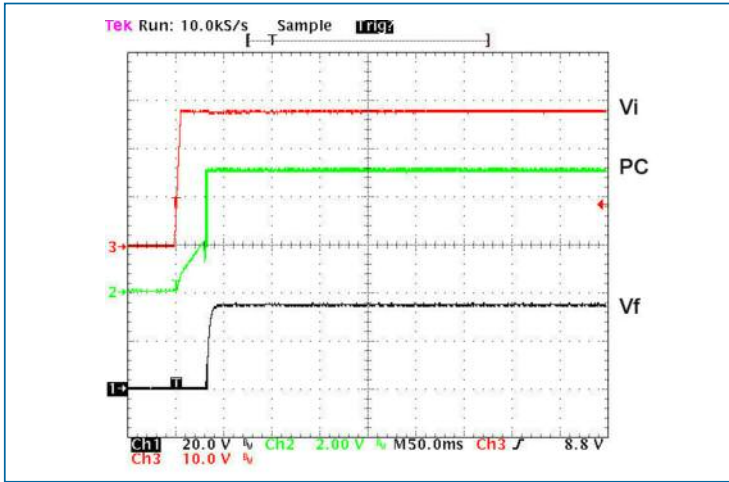


Figure 1 — Vf and PC response from power up

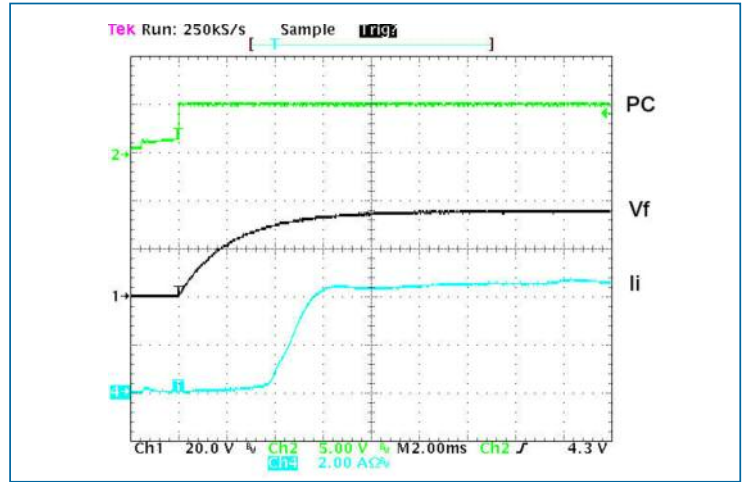


Figure 2 — Vf turn-on waveform with inrush current – PC enabled at full load, 28 Vin, electronic load set @constant R.

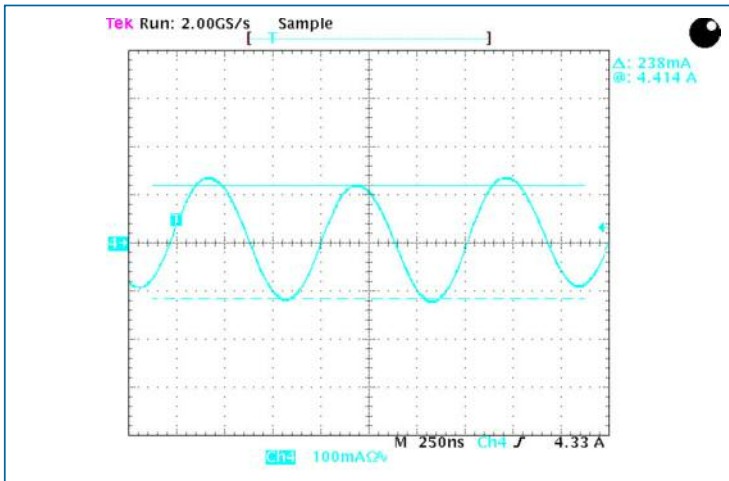
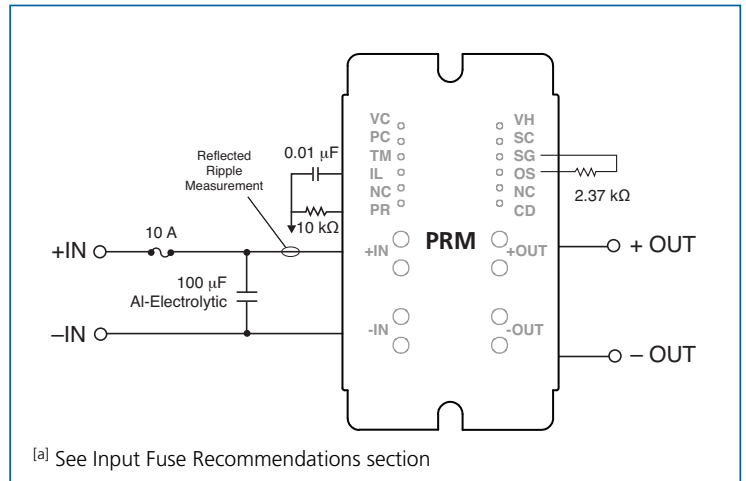


Figure 3 — Input reflected ripple current at full load and 28 Vin



[a] See Input Fuse Recommendations section

Figure 4 — Input filter capacitor recommendation

SPECIFICATIONS (CONT.)

EFFICIENCY GRAPHS

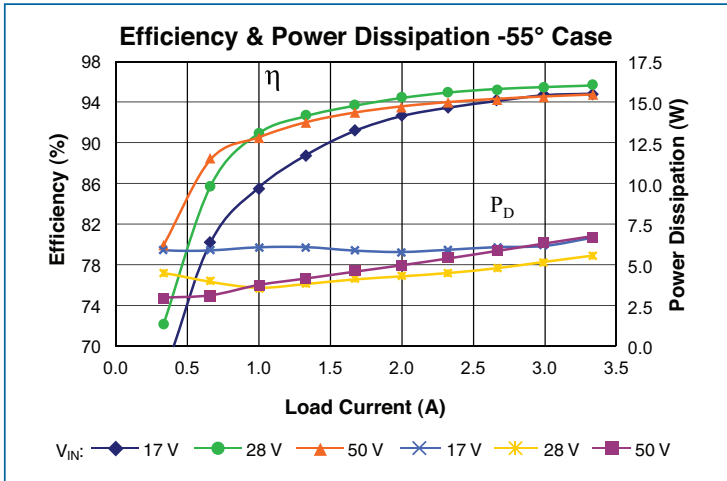


Figure 5 — Efficiency vs. output current at 48 Vf

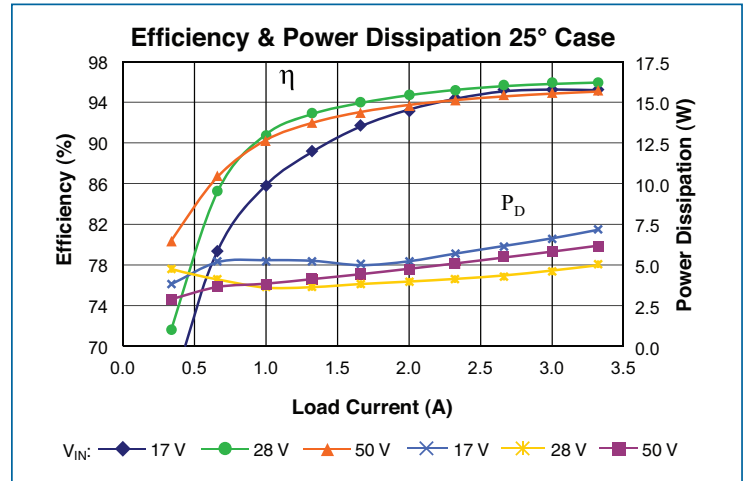


Figure 6 — Efficiency vs. output current at 36 Vf

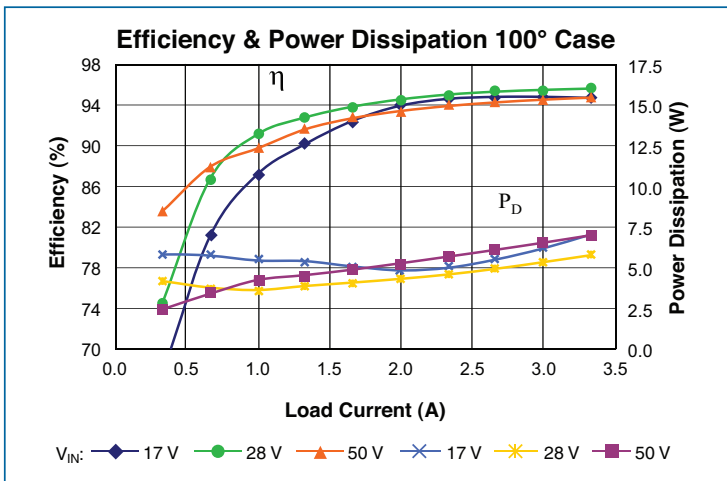


Figure 7 — Efficiency vs. output current at 26 Vf

SPECIFICATIONS (CONT.)

OUTPUT WAVEFORMS

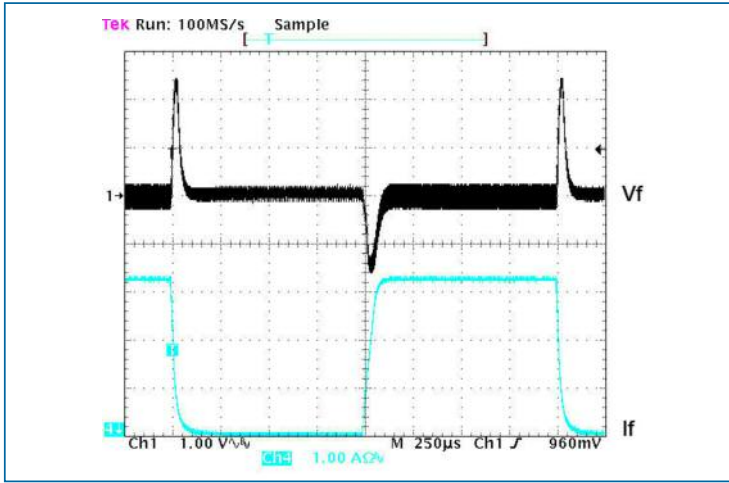


Figure 8 — Transient response; PRM alone 28 Vin, 0-3.3-0A, no load capacitance, local loop

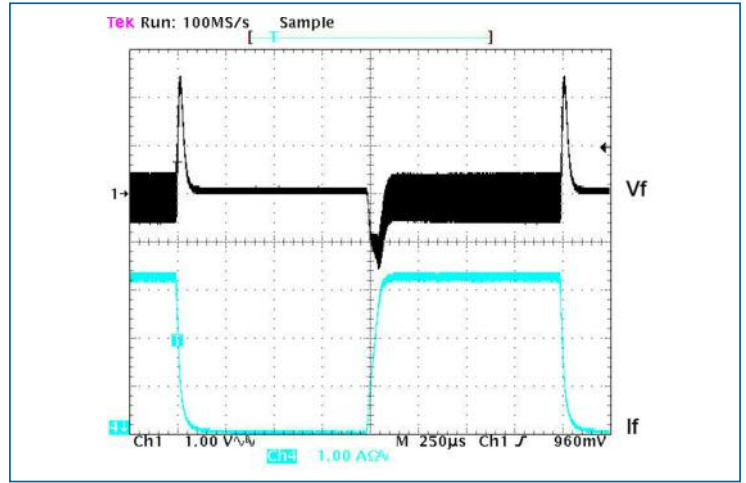


Figure 9 — Transient response; PRM alone 16 Vin, 0-3.3-0A no load capacitance, local loop

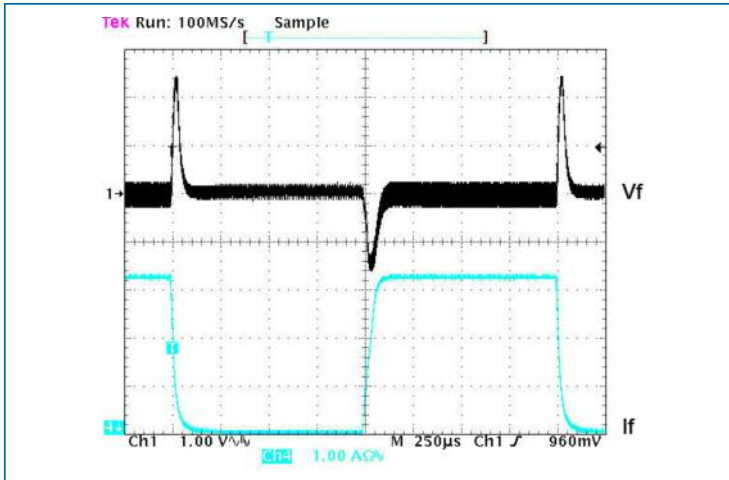


Figure 10 — Transient response; PRM alone 50 Vin, 0-3.3-0A no load capacitance, local loop

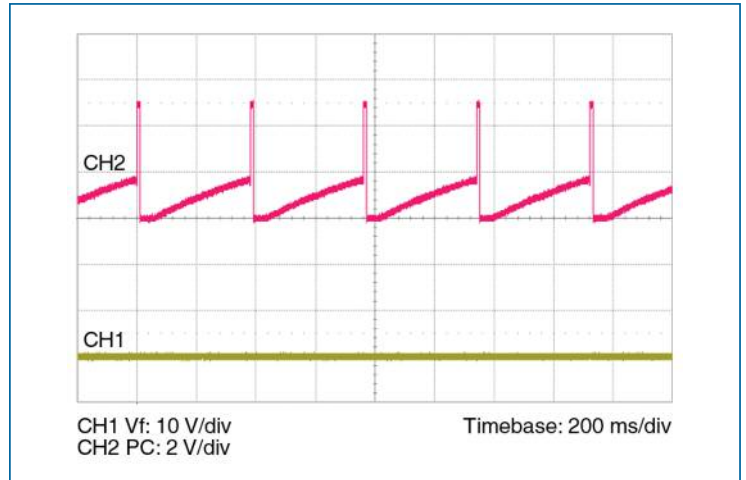


Figure 11 — PC during fault – frequency will vary as a function of line voltage

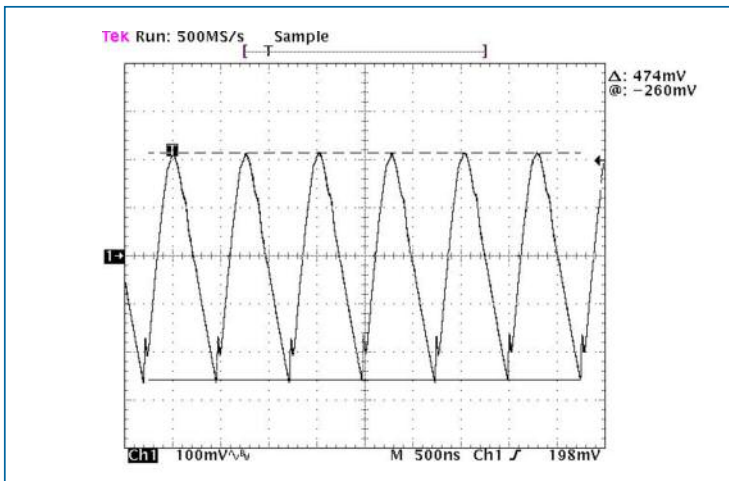


Figure 12 — Output ripple 36 Vf, full load no bypass capacitance

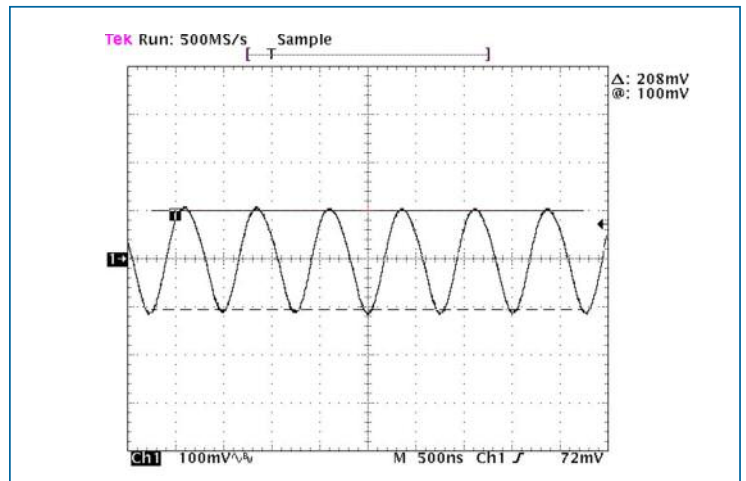


Figure 13 — Output ripple 36 Vf, full load 10µF bypass capacitance

## SPECIFICATIONS (CONT.)

## General Specifications

Parameter	Min	Typ	Max	Unit	Notes
MTBF					
MIL-HDBK-217F		3,455,898		hrs	25°C, GB
		621,888		hrs	50°C, NS
		487,281		hrs	65°C, AIC
Agency approvals					
		CTÜVus			UL/CSA 60950-1, EN60950-1
		CE Mark			Low voltage directive
Isolation					
Input to Output					Not applicable
Input to Case		2,250		Vdc	
Output to Case		2,250		Vd	
Mechanical parameters					
Weight		1.07/30,4		oz/g	See Mechanical Drawings, Figures 19 & 20
Dimensions					
Length		1.91/48,6		in/mm	
Width		1.09/27,7		in/mm	
Height		0.37/9,5		in/mm	
Thermal					
Over temperature shutdown	130	135	140	°C	junction temperature
Thermal capacity		23.8		Ws/°C	
Baseplate to ambient		8.8		°C/W	
Baseplate to ambient; 1000 LFM		3.0		°C/W	
Baseplate to sink; flat, greased surface		0.40		°C/W	
Baseplate to sink; thermal pad		0.36		°C/W	

## SPECIFICATIONS (CONT.)

Auxiliary Pins					
Parameter	Min	Typ	Max	Unit	Notes
VC (VTM Control)					
Pulse width	8	12	18	ms	
Peak voltage		14	18	V	Referenced to –In
PC (Primary Control)					
DC voltage	4.8	5.0	5.2	Vdc	Referenced to –In
Module disable voltage	2.3	2.4		Vdc	Referenced to –In
Module enable voltage		2.5	2.6	Vdc	
Disable hysteresis		100		mV	
Current limit		1.75	1.90	mA	Source only after start up; not to be used for aux. supply; 100 k $\Omega$ minimum load impedance to assure start up.
Enable delay time		100		$\mu$ s	
Disable delay time		1		$\mu$ s	
IL (Current Limit Adjust)					
Voltage	0.95	1	1.05	V	
Accuracy		$\pm 15$		%	Based on DC current limit set point
PR (Parallel Port)					
Voltage	2.5		3.5	V	Referenced to SG; See description Page 7
Source current	1			mA	
External capacitance			100	pF	
VH (Auxiliary Voltage)					
Range	8.7	9.0	9.3	Vdc	Typical internal bypass C=0.1 $\mu$ F Maximum external C=0.1 $\mu$ F, referenced to SG
Regulation		0.04		%/mA	
Current			5	mA p	
SC (Secondary Control)					
Voltage	1.23	1.24	1.25	Vdc	Referenced to SG
Internal capacitance		0.22		$\mu$ F	
External capacitance			0.7	$\mu$ F	
OS (Output Set)					
Set point accuracy		$\pm 1.5$		%	Includes 1% external resistor
Reference offset		$\pm 4$		mV	
CD (Compensation Device)					
External resistance	20			$\Omega$	Omit resistor for regulation at output of PRM



## PIN / CONTROL FUNCTIONS

### +In / -In DC Voltage Ports

The VI BRICK® maximum input voltage should not be exceeded. PRMs have internal over / undervoltage lockout functions that prevent operation outside of the specified input range. PRMs will turn on when the input voltage rises above its undervoltage lockout. If the input voltage exceeds the overvoltage lockout, PRMs will shut down until the overvoltage fault clears. PC will toggle indicating an out of bounds condition.

### +Out / -Out Factorized Voltage Output Ports

These ports provide the Factorized Bus voltage output. The -Out port is connected internally to the -In port through a current sense resistor. The PRM has a maximum power and a maximum current rating and is protected if either rating is exceeded. Do not short -Out to -In.

### VC – VTM Control

The VTM® Control (VC) port supplies an initial  $V_{CC}$  voltage to downstream VTMs, enabling the VTMs and synchronizing the rise of the VTM output voltage to that of the PRM. The VC port also provides feedback to the PRM to compensate for voltage drop due to the VTM output resistance. The PRM's VC port should be connected to the VTM VC port. A PRM VC port can drive a maximum of two (2) VTM VC ports.

### PC – Primary Control

The PRM voltage output is enabled when the PC pin is open circuit (floating). To disable the PRM output voltage, the PC pin is pulled low. Open collector optocouplers, transistors, or relays can be used to control the PC pin. When using multiple PRMs in a high power array, the PC ports must be tied together to synchronize their turn on. During an abnormal condition the PC pin will pulse (Fig.11) as the PRM initiates a restart cycle. This will continue until the abnormal condition is rectified. The PC should not be used as an auxiliary voltage supply, nor should it be switched at a rate greater than 1 Hz.

### TM – Factory Use Only

### IL – Current Limit Adjust

The PRM has a preset, maximum, current limit set point. The IL port may be used to reduce the current limit set point to a lower value. See “adjusting current limits” on page 10.

### PR – Parallel Port

The PR port signal, which is proportional to the PRM output power, supports current sharing of two PRMs. To enable current sharing, PR ports should be interconnected. Bypass capacitance should be used when interconnecting PR ports and steps should be taken to minimize coupling noise into the interconnecting bus. Terminate this port with a 10 k equivalent resistance to SG, e.g. 10 k for a single PRM, 20 k each for 2 PRMs in parallel, 30 k each for 3 PRMs in parallel etc.. Please consult Vicor Applications Engineering regarding additional considerations when paralleling more than two PRMs.

### VH – Auxiliary Voltage

VH is a gated (e.g. mirrors PC), non-isolated, nominally 9 Volt, regulated DC voltage (see “Auxiliary Pins” specifications, on Page 6) that is referenced to SG. VH may be used to power external circuitry having a total current consumption of no more than 5 mA under either transient or steady state conditions including turn-on.

### SC – Secondary Control

The load voltage may be controlled by connecting a resistor or voltage source to the SC port referenced to SG. The slew rate of the output voltage may be controlled by controlling the rate-of-rise of the voltage at the SC port (e.g., to limit inrush current into a capacitive load).

### SG – Signal Ground

This port provides a low inductance Kelvin connection to -In and should be used as reference for the OS, CD, SC, VH and IL ports.

### OS – Output Set

The application-specific value of the Factorized Bus voltage ( $V_f$ ) is set by connecting a resistor between OS and SG. Resistor value selection is shown in Table 1 on Page 8, and described on Page 9. If no resistor is connected, the PRM output will be approximately one volt. If set resistor is not collocated with the PRM, a local bypass capacitor of ~200 pF may be required.

### CD – Compensation Device

Adaptive Loop control is configured by connecting an external resistor between the CD port and SG. Selection of an appropriate resistor value (see Equation 2 on Page 9 and Table 1 on Page 8) configures the PRM to compensate for voltage drops in the equivalent output resistance of the VTM and the PRM-VTM distribution bus. If no resistor is connected to CD, the PRM will be in Local Loop mode and will regulate the +Out / -Out voltage to a fixed value.

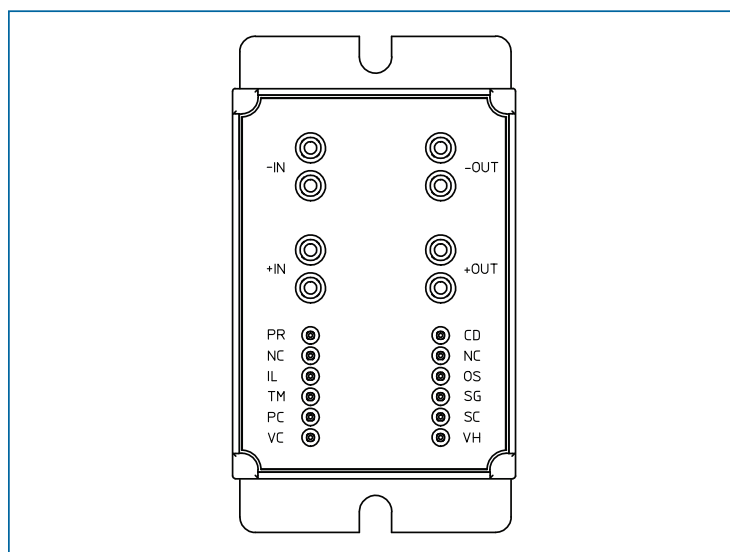


Figure 14 — VI Brick PRM pin configuration (viewed from pin side).

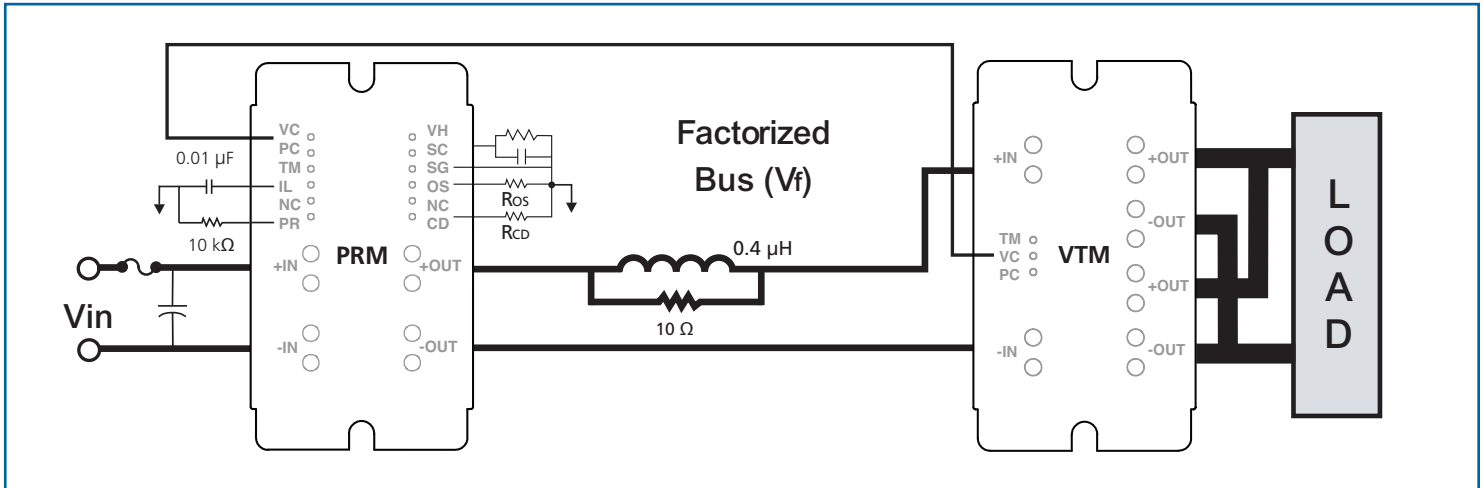
## APPLICATION INFORMATION

## Overview of Adaptive Loop Compensation

Adaptive Loop compensation, illustrated in Figure 15, contributes to the bandwidth and speed advantage of Factorized Power. The PRM monitors its output current and automatically adjusts its output voltage to compensate for the voltage drop in the output resistance of the VTM<sup>®</sup>.  $R_{OS}$  sets the desired value of the VTM output voltage,  $V_{out}$ ;  $R_{CD}$  is set to a value that compensates for the output resistance of the VTM (which, ideally, is located at the point of load). For selection of  $R_{OS}$  and  $R_{CD}$ , refer to Table 1 below or Page 9.

The VI Brick's bi-directional VC port :

1. Provides a wake up signal from the PRM to the VTM that synchronizes the rise of the VTM output voltage to that of the PRM.
2. Provides feedback from the VTM to the PRM to enable the PRM to compensate for the voltage drop in VTM output resistance,  $R_O$ .



**Figure 15** — With Adaptive Loop control, the output of the VTM is regulated over the load current range with only a single interconnect between the PRM and VTM and without the need for isolation in the feedback path.

Desired Load Voltage (Vdc)	VI BRICK VTM P/N <sup>[1]</sup>	Max VTM Output Current (A) <sup>[2]</sup>	$R_{OS}$ (k $\Omega$ ) <sup>[3]</sup>	$R_{CD}$ ( $\Omega$ ) <sup>[3]</sup>
1.0	MT036A011M100FP	100	2.70	34.8
1.2	MT036A011M100FP	100	2.24	41.2
1.5	MT036A015M080FP	80	2.39	32.4
1.8	MT036A015M080FP	80	1.98	38.3
2.0	MT036A022M055FP	55	2.70	23.2
3.3	MT036A030M040FP	40	2.16	37.4
5.0	MT036A045M027FP	27	2.14	39.2
10	MT036A090M013FP	13.3	2.14	41.2
12	MT036A120M010FP	10	2.39	21.5
15	MT036A180M007FP	6.7	2.87	34.8
24	MT036A240M005FP	5.0	2.39	38.3
28	MT036A240M005FP	5.0	2.04	41.2
36	MT036A360M003FP	3.3	2.39	34.8
48	MT036A360M003FP	3.3	1.78	45.3

**Note:**

<sup>[1]</sup> See Table 2 on Page 9 for nominal  $V_{out}$  range and K factors

<sup>[2]</sup> See "PRM output power vs. VTM output power" on Page 10

<sup>[3]</sup> 1% precision resistors recommended

**Table 1** — Configure your Chip Set using the VI Brick PRM.

APPLICATION INFORMATION

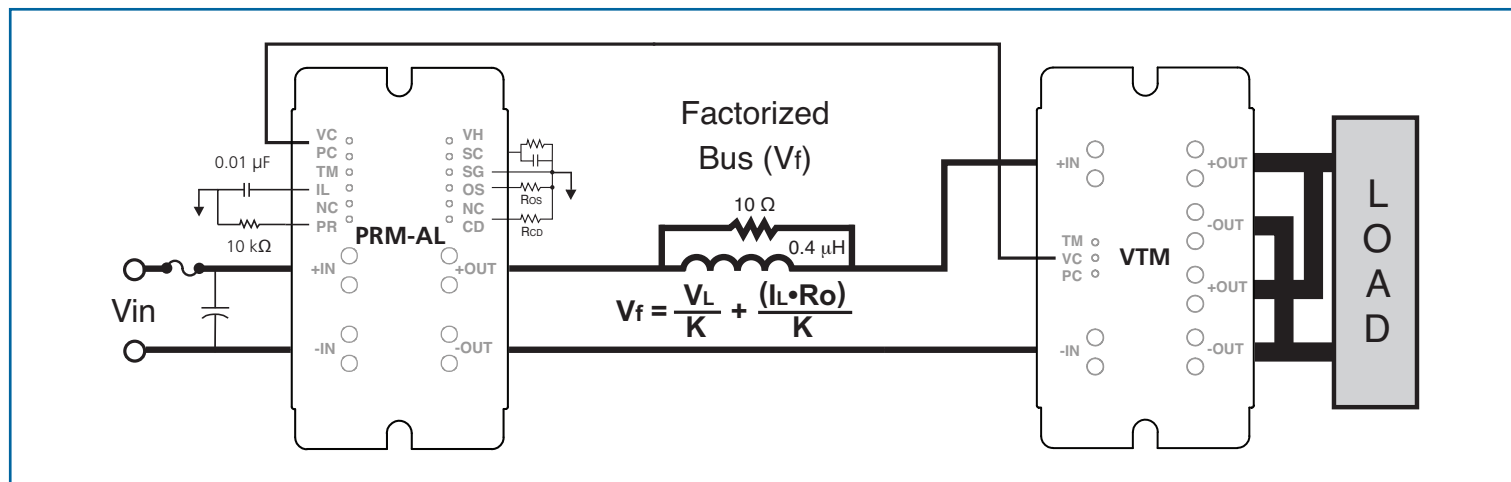


Figure 16 — Adaptive Loop compensation with soft start using the SC port.

Output Voltage Setting with Adaptive Loop

The equations for calculating  $R_{OS}$  and  $R_{CD}$  to set a VTM<sup>®</sup> output voltage are:

$$R_{OS} = \frac{69800}{\left(\frac{V_L \cdot 0.8395}{K}\right) - 1} \quad (1)$$

$$R_{CD} = \frac{68404}{R_{OS}} + 1 \quad (2)$$

$V_L$  = Desired load voltage

$V_{OUT}$  = VTM output voltage

$K$  = VTM transformation ratio  
(available from appropriate VTM data sheet)

$V_f$  = PRM output voltage, the Factorized Bus (see Figure 16)

$R_O$  = VTM output resistance  
(available from appropriate VTM data sheet)

$I_L$  = Load Current  
(actual current delivered to the load)

Output Voltage Trimming (optional)

After setting the output voltage from the procedure above the output may be margined down ( $26 V_f \text{ min}$ ) by a resistor from SC-SG using this formula:

$$R_{\Omega} = \frac{10000 V_{fd}}{V_{fs} - V_{fd}}$$

Where  $V_{fd}$  is the desired factorized bus and  $V_{fs}$  is the set factorized bus.

A low voltage source can be applied to the SC port to margin the load voltage in proportion to the SC reference voltage.

An external capacitor can be added to the SC port as shown in Figure 16 to control the output voltage slew rate for soft start.

Nominal Vout Range (Vdc)	VTM K Factor
0.8 ↔ 1.6	1/32
1.1 ↔ 2.0	1/24
1.7 ↔ 3.1	1/16
2.2 ↔ 4.1	1/12
3.3 ↔ 6.2	1/8
4.3 ↔ 8.3	1/6
5.2 ↔ 10.0	1/5
6.5 ↔ 12.5	1/4
8.7 ↔ 16.6	1/3
13.0 ↔ 25.0	1/2
17.4 ↔ 33.3	2/3
26.0 ↔ 50.0	1

Table 2 — 036 input series VTM K factor selection guide

## APPLICATION NOTES

### OVP – Overvoltage Protection

The output Overvoltage Protection set point of the MR028A036M012FP is factory preset for 56 V. If this threshold is exceeded the output shuts down and a restart sequence is initiated, also indicated by PC pulsing. If the condition that causes OVP is still present, the unit will again shut down. This cycle will be repeated until the fault condition is removed. The OVP set point may be set at the factory to meet unique high voltage requirements.

### PRM Output Power Versus VTM Output Power

As shown in Figure 17, the MR028A036M012FP is rated to deliver 3.3 A maximum, when it is delivering an output voltage in the range from 26 V to 36 V, and 120 W, maximum, when delivering an output voltage in the range from 36 V to 50 V. When configuring a PRM for use with a specific VTM®, refer to the appropriate VTM data sheet. The VTM input power can be calculated by dividing the VTM output power by the VTM efficiency (available from the VTM data sheet). The input power required by the VTM should not exceed the output power rating of the PRM.

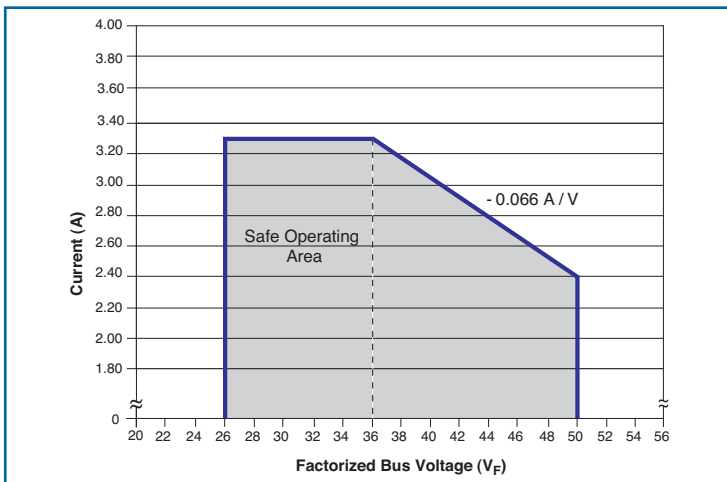


Figure 17 — MR028A036M012FP rating based on Factorized Bus voltage

The Factorized Bus voltage should not exceed an absolute limit of 55 V, including steady state, ripple and transient conditions. Exceeding this limit may cause the internal OVP set point to be exceeded.

### Parallel Considerations

The PR port is used to connect two PRMs in parallel to form a higher power array. When configuring arrays, PR port interconnection terminating impedance is 10 k to SG. See note Page 7 and refer to Application Note AN002. Additionally one PRM should be designated as the master while all other PRMs are set as slaves by shorting their SC pin to SG. The PC pins must be directly connected (no diodes) to assure a uniform start up sequence. Consult Vicor applications engineering for applications requiring more than two PRMs.

### Adjusting Current Limit

The current limit can be lowered by placing an external resistor between the I<sub>L</sub> and SG ports (see Figure 18 for resistor values). With the I<sub>L</sub> port open-circuit, the current limit is preset to be within the range specified in the output specifications table on Page 2.

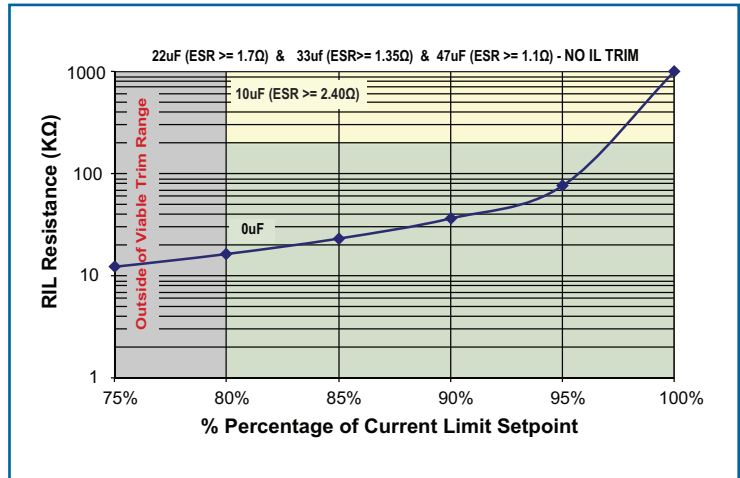


Figure 18 — Calculated external resistor value for adjusting current limit, actual value may vary.

### Input Fuse Recommendations

A fuse should be incorporated at the input to the PRM, in series with the +In port. A fast acting fuse, NANO2 FUSE 451/453 Series 10 A 125 V, or equivalent, may be required to meet certain safety agency Conditions of Acceptability. Always ascertain and observe the safety, regulatory, or other agency specifications that apply to your specific application. Please see [vicorpower.com](http://vicorpower.com) for agency approvals and fusing conditions.

### Product Safety Considerations

If the input of the PRM is connected to SELV or ELV circuits, the output of the PRM can be considered SELV or ELV respectively.

If the input of the PRM is connected to a centralized DC power system where the working or float voltage is above SELV, but less than or equal to 75 V, the input and output voltage of the PRM should be classified as a TNV-2 circuit and spaced 1.3 mm from SELV circuitry or accessible conductive parts according to the requirements of UL60950-1, CSA 22.2 60950-1, EN60950-1, and IEC60950-1.

### Application Notes

For PRM and VI Brick® application notes on soldering, board layout, and system design please click on the link below:

[www.vicorpower.com/application-notes](http://www.vicorpower.com/application-notes)

### Applications Assistance

Please contact Vicor Applications Engineering for assistance, 1-800-927-9474, or email at [apps@vicorpower.com](mailto:apps@vicorpower.com).

MECHANICAL DRAWINGS

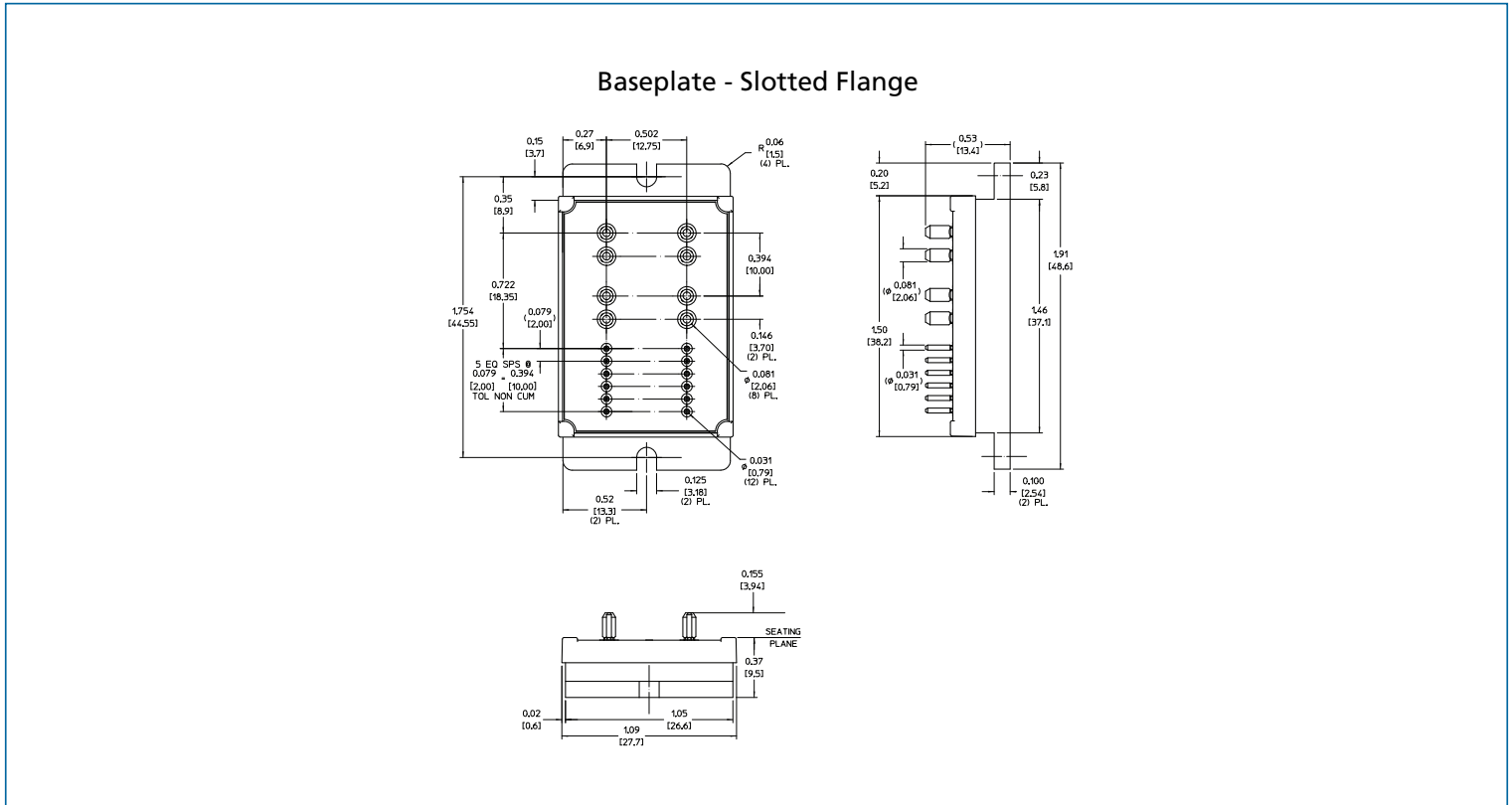


Figure 19 — Module outline

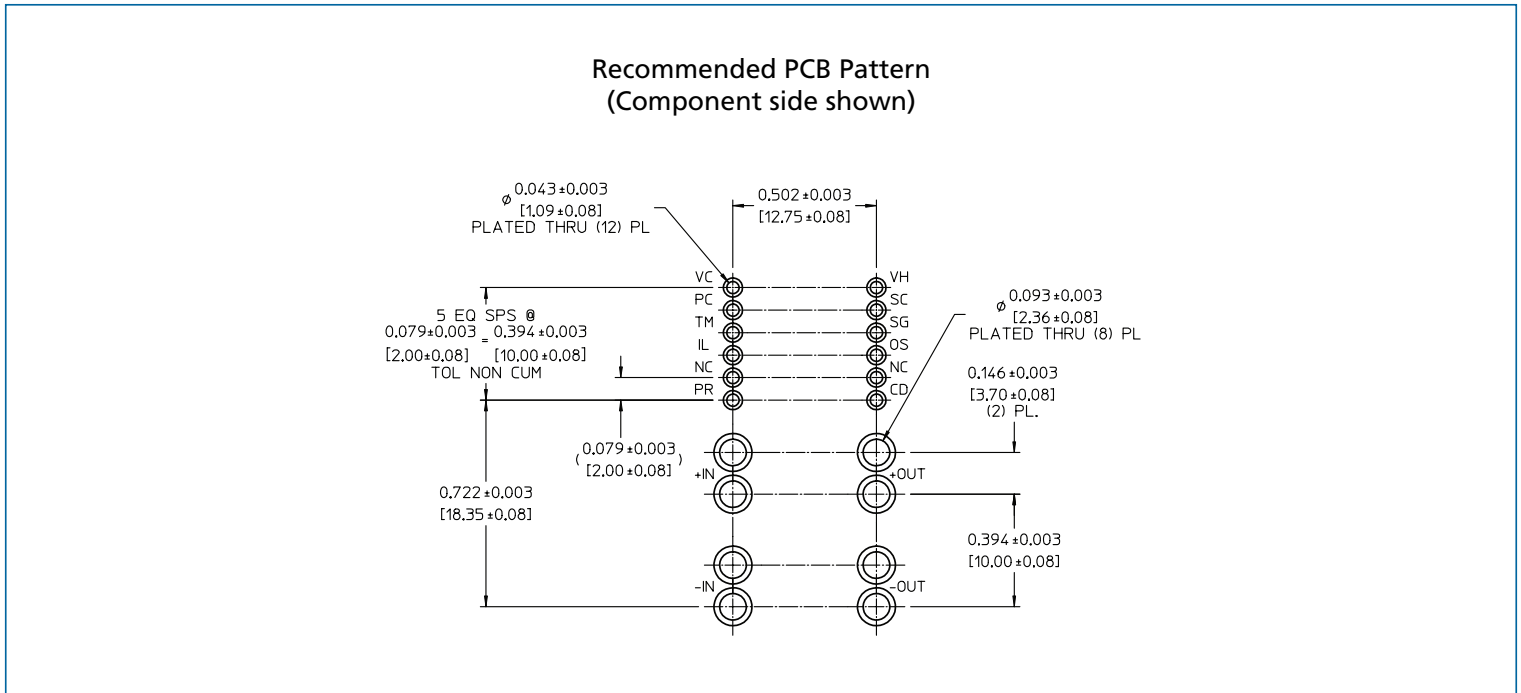


Figure 20 — PCB mounting specifications

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